

# UAV-based Remote Sensing Payload Comprehensive Validation System

**Chuan-rong LI**

**Project PI**



**Academy of Opto-Electronics (AOE),  
Chinese Academy of Sciences (CAS)**

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# Outline



**1** Background

**2** System Overview

**3** Inflight Calibration & Performance Assessment

**4** Future Plan

# 1. Background



*Trend of Earth observation systems:*

**Quantitative  
remote sensing  
application**



**International  
standardization  
of data quality  
assessment and  
data sharing**

**Pre-launch Cal  
& Val demand**

**Monitoring of  
payload  
performance in  
system operation  
period**



# 1. Background



## LOW COST

Development cost: 10% of manned aircraft  
Operation cost: 10% of manned aircraft

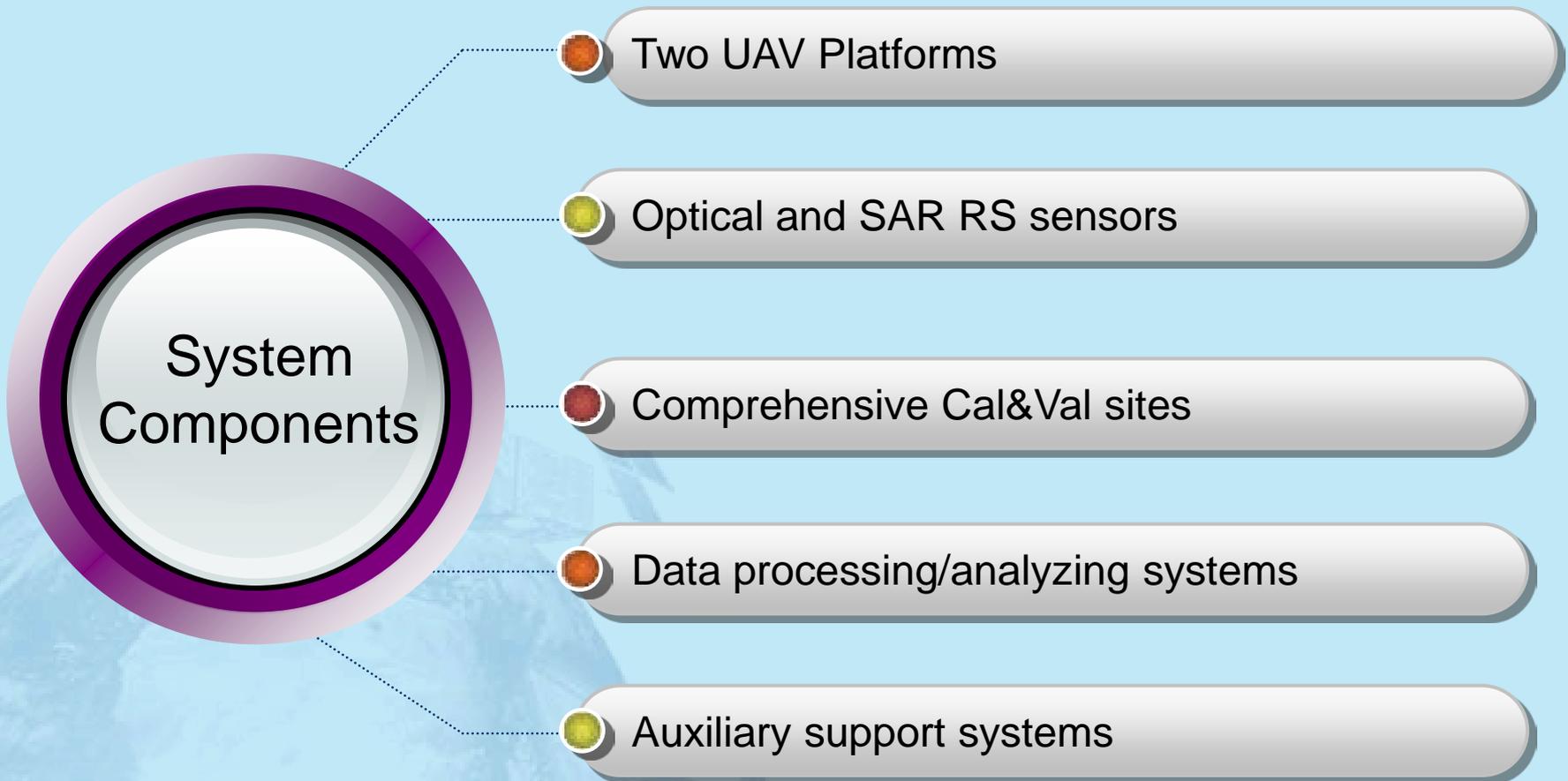
**Why UAV?**

Provide realistic validation environments (telemetry, telecontrol, etc)

Carry out flight experiment in specific scenarios

**UAV-based Remote Sensing Payload Comprehensive Validation System**

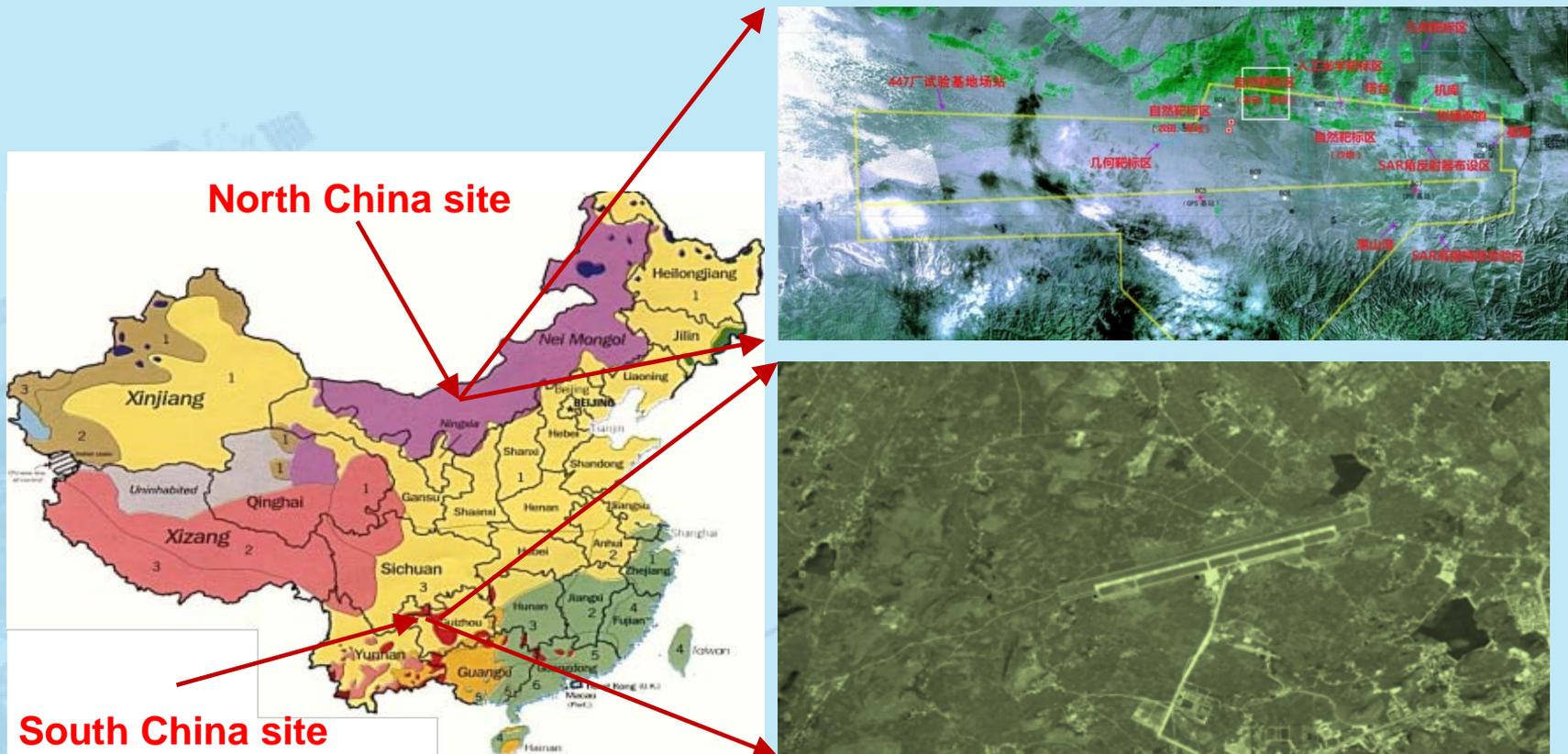
## 2. System Overview



## 2. System Overview - The Comprehensive C&V Site



- Two comprehensive Cal&Val test sites were preliminarily established, which have different climate characteristics, various land cover types and topographic features.
- Now they are being further developed so as to support multi-grade validation of airborne and spaceborne sensors **for stable and long-term operation.**



# 2. System Overview - The Comprehensive C&V Site



- Standard artificial and natural targets



Knife-edge target



Fan-shaped target



Gray-scale target



Colored target



Three-bar target



Layout of targets

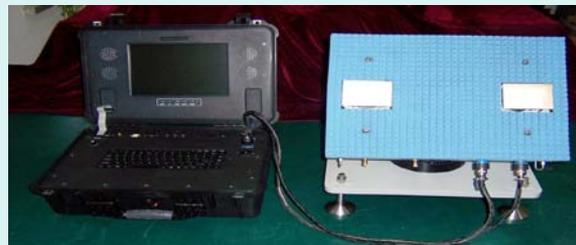
## Optical targets



Trihedral Corner Reflector



Dihedral Corner Reflectors



Ku-band Active Transponder



## SAR targets



Rice



Maize



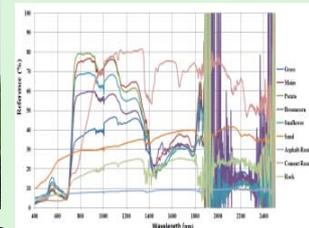
Potato



Sunflower



Surface parameters measurement



Spectral curves

## Natural ground targets

# 2. System Overview - Data processing/analyzing system



## Data processing/analyzing system

### Data processing

- Radiometric correction
- Geometric correction
- Spectral correction
- Reflectance retrieval
- Vegetation index retrieval
- SAR data processing

### Radiometric performance assessment

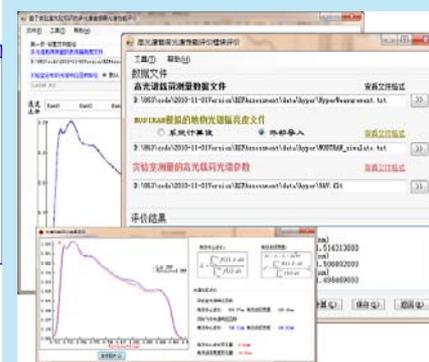
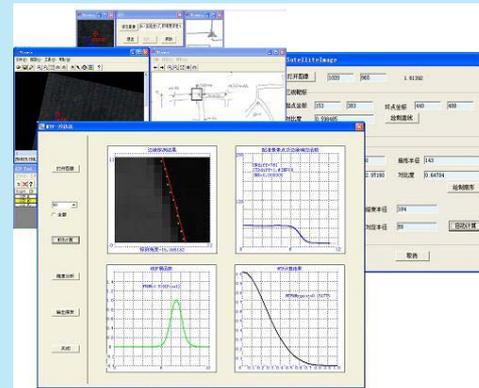
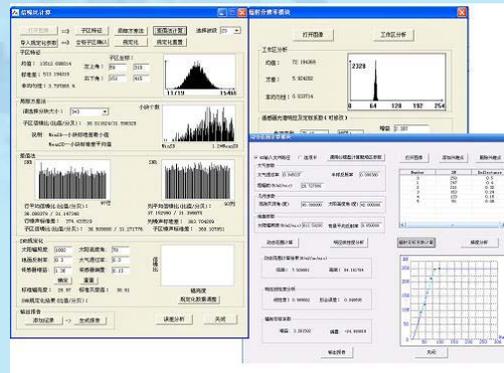
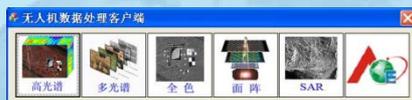
- Absolute radiometric calibration
- Signal to Noise Ratio, SNR
- Dynamic range
- Response linear degree
- Radiometric resolution,  $NE\Delta\rho$

### Geometric Performance Assessment

- Ground resolution
- MTF
- Band registration precision

### Spectral Performance Assessment

- Hyperspectral camera: central bandwidth; FWHM
- Multispectral camera: spectral response function



### 3. Inflight Calibration & Performance Assessment



- **Flight campaigns**

- **Nov 2010 Campaign**

*Airborne optical sensors in North China test site*

- **Jul 2011 Campaign**

*Airborne optical and SAR sensors in South China test site*

- **Sep 2011 Campaign**

*Airborne optical and SAR sensors in North China test site*

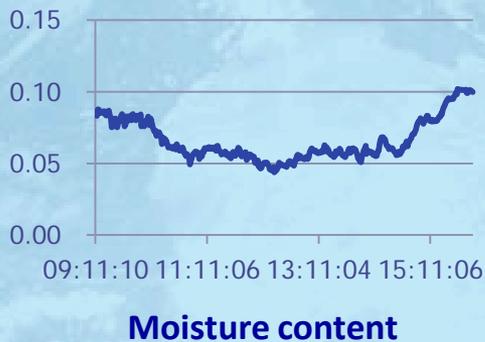
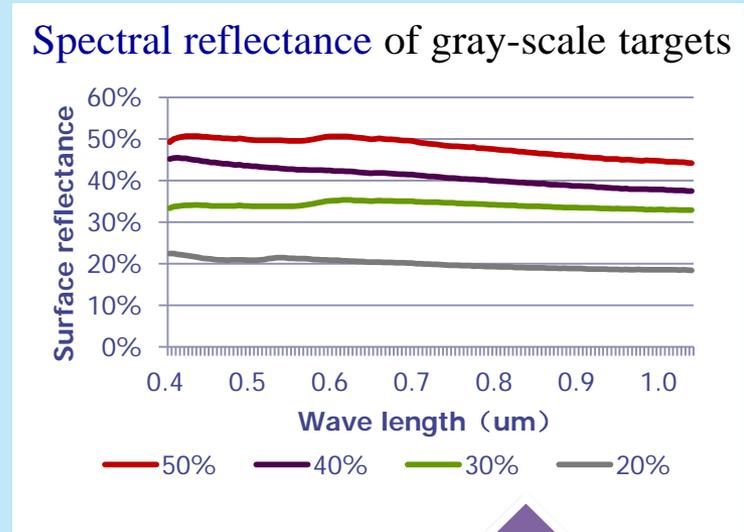
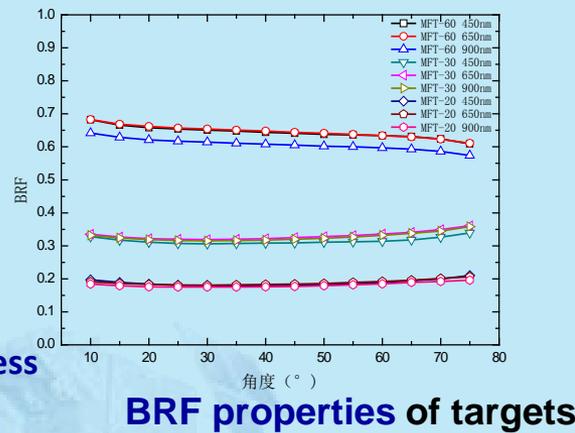


# 3. Inflight Calibration & Performance Assessment



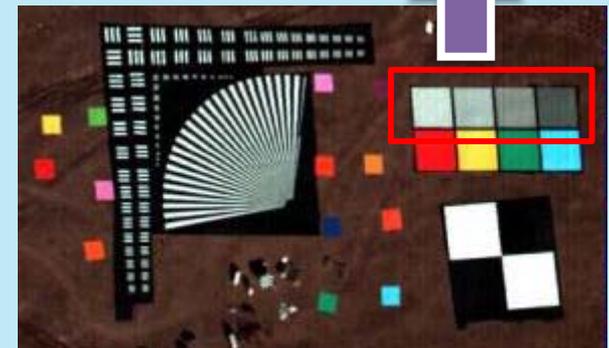
## • Atmospheric and field measurements

Spectral reflectance of targets were measured. The aerosol optical thickness data and meteorological profile above the test site **were synchronously collected**.



Automatic sun tracking photometer, CE318

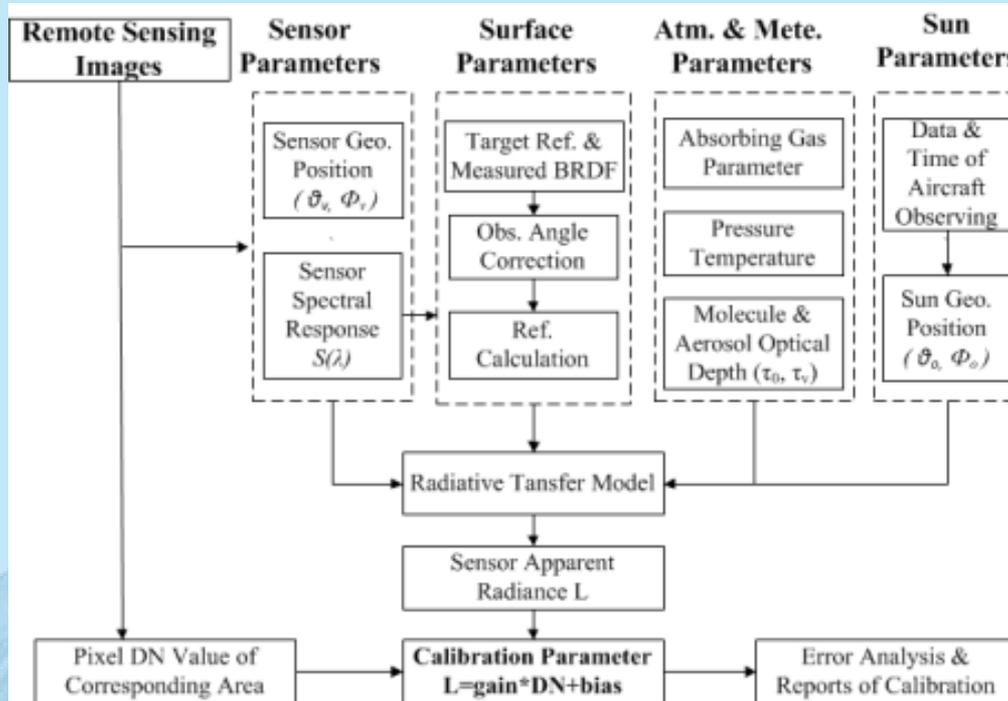
Automatic weather station



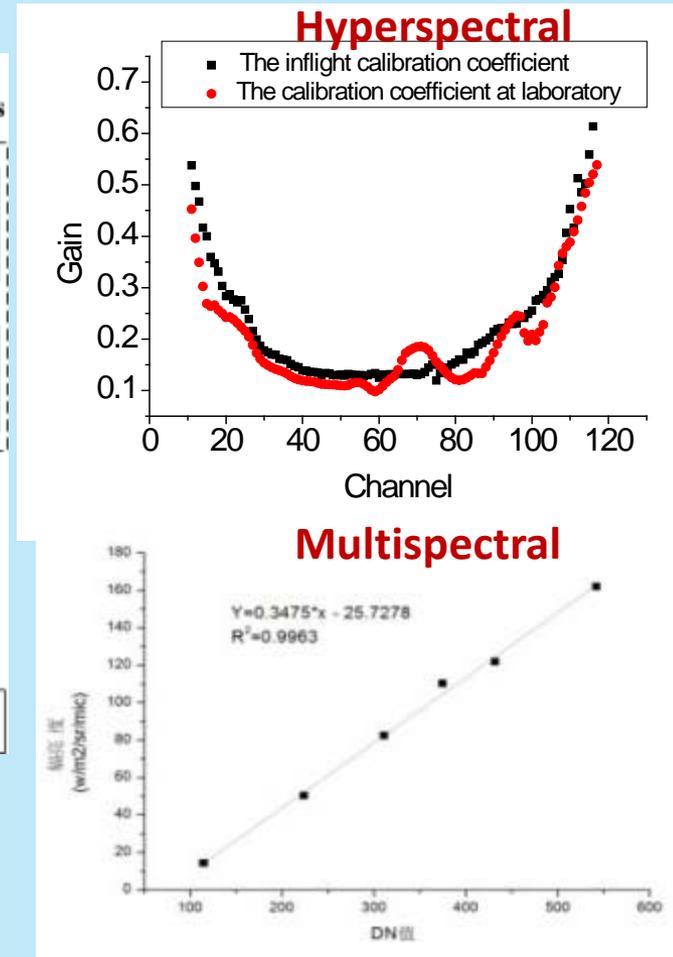
# 3. Inflight Calibration & Performance Assessment



## • Cal&Val of Optical sensors – Absolute radiometric calibration



Flow chart of optical sensor radiometric calibration



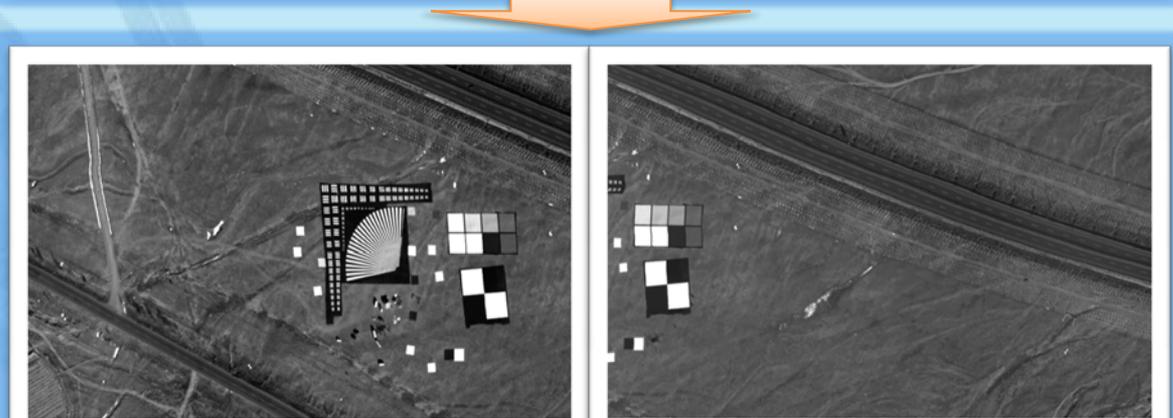
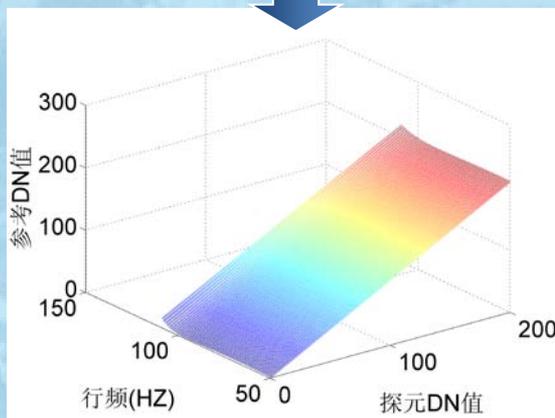
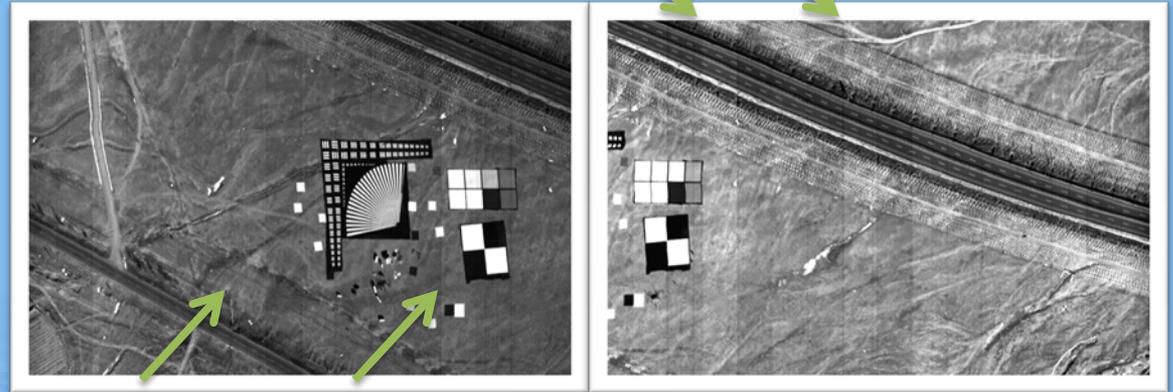
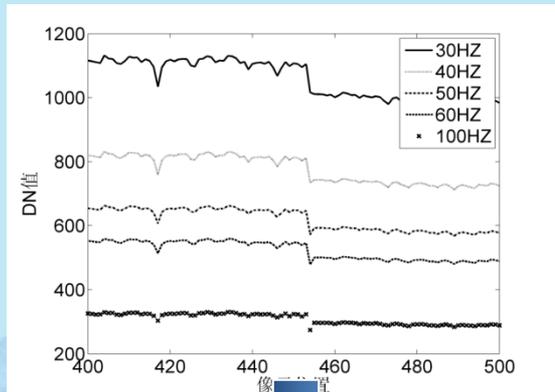
Radiometric calibration coefficients have very good linearity and the correlation coefficient reaches above 99%.

### 3. Inflight Calibration & Performance Assessment



#### • Cal&Val of Optical sensors – Relative radiometric calibration

- Because of the variation in velocity height ratio, the images of hyperspectral imager between adjacent flight strips lack of comparability for different surfaces.
- A relative radiometric calibration method based on line frequency difference is proposed to solve this problem.



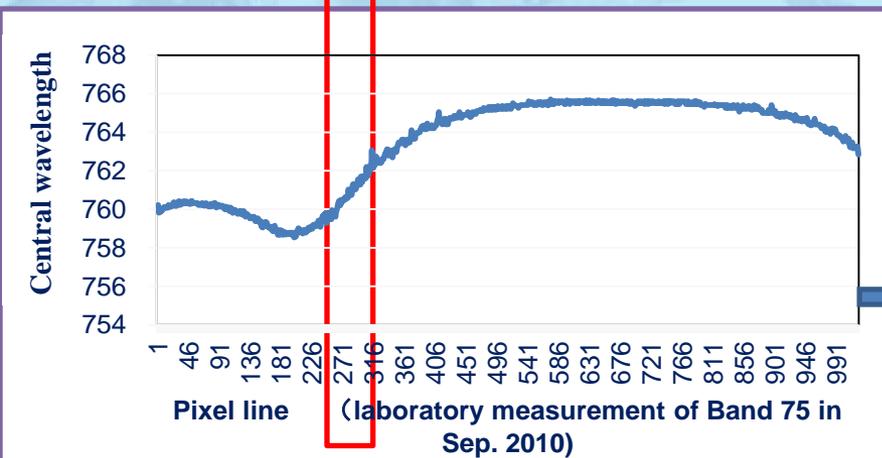
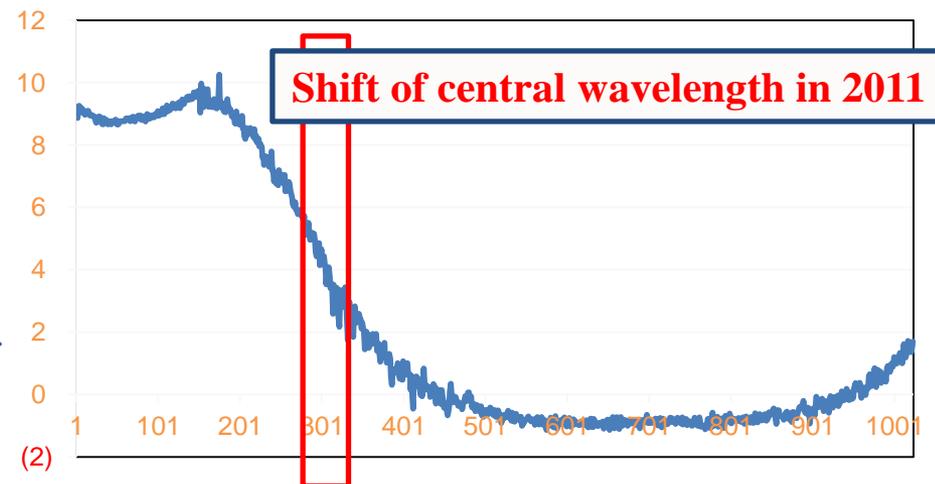
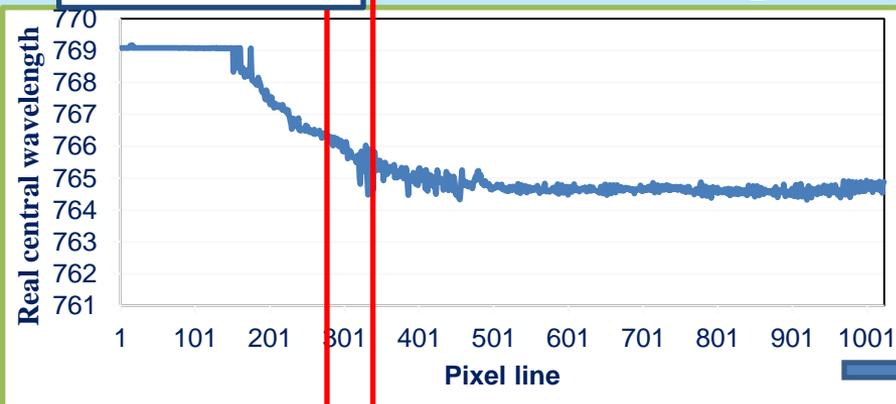
### 3. Inflight Calibration & Performance Assessment



- Cal&Val of Optical sensors– Spectral calibration
  - Spectral calibration for hyperspectral sensor

- Retrieval central wavelength based on flight data in 2011.
- Band 75 is O<sub>2</sub> absorption band.

280~315 line



The shift of central wavelength is approximately 4~6nm compared to laboratory measurement.

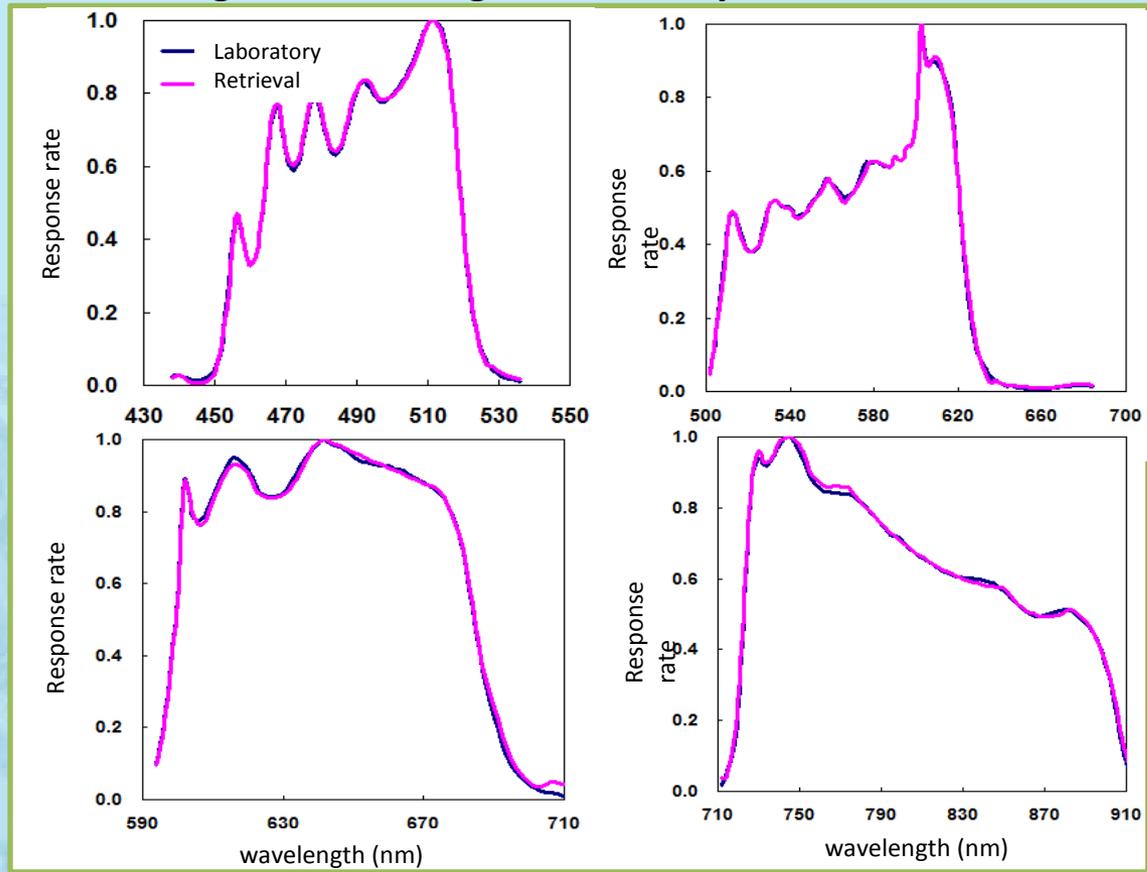
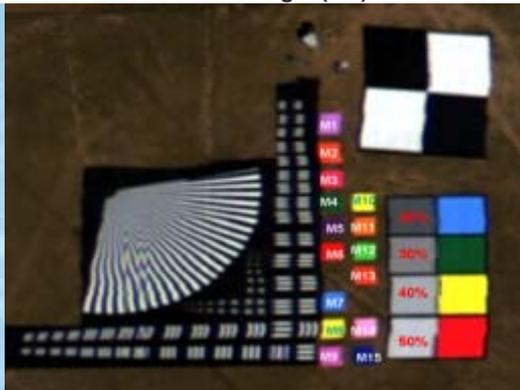
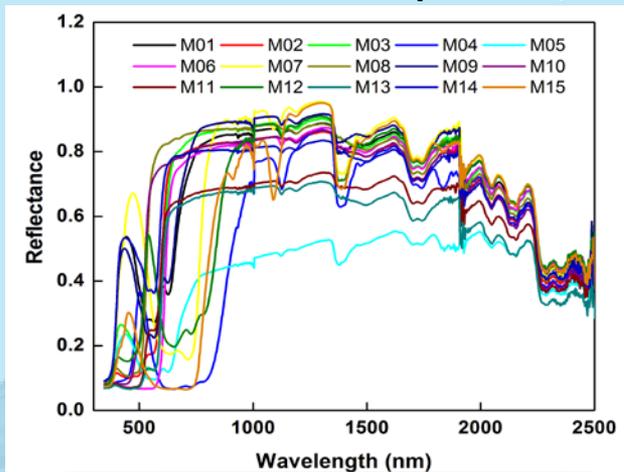
### 3. Inflight Calibration & Performance Assessment



- Cal&Val of Optical sensors– Spectral calibration

- Spectral calibration for multispectral sensor

- **Difficulty:** Solving of spectral response function faces ill-condition matrix
    - **Solutions:** The spectral reflectance of 15 multispectral targets were measured to add the number of equations; Piecewise fitting SRF according to laboratory measurements

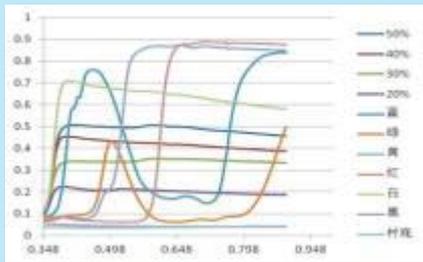


# 3. Inflight Calibration & Performance Assessment

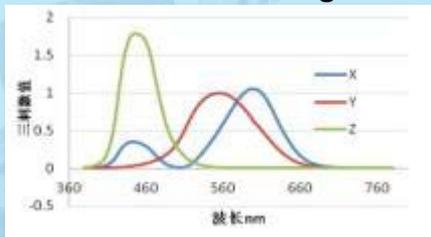


## • Cal&Val of Optical sensors– True-color calibration

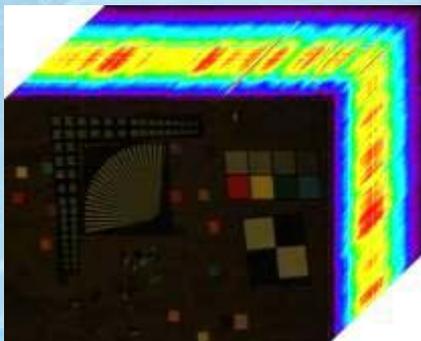
A general true color calibration model is proposed based on the physical mechanism of color generation, which can fully employed all spectral information in VNIR reflection zones of hyperspectral images.



In-situ measured spectral reflectance of the targets

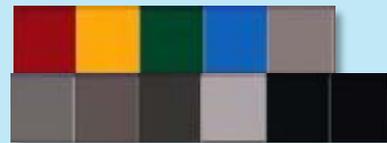


Human visual color matching function



At-sensor radiance HSI image

①



At-sensor ideal true color of the targets

②



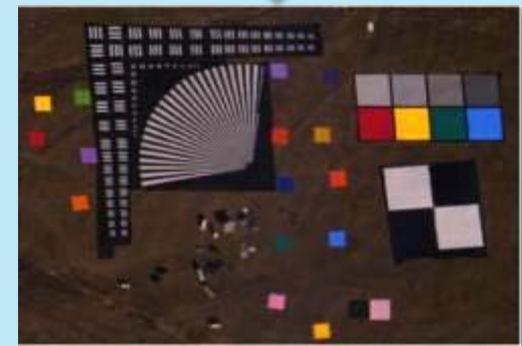
Reconstructed true color of the targets & Images before true color correction

③

$$M_{RGB \rightarrow R'G'B'} = \begin{bmatrix} 2.5635 & -0.3903 & -0.2178 \\ -0.1077 & 3.7997 & 0.5655 \\ 0.0416 & 0.2628 & 12.4262 \end{bmatrix}$$

True-color correction coefficient matrix

④



The corrected true-colored image

④  
True-color correction

MODTRAN

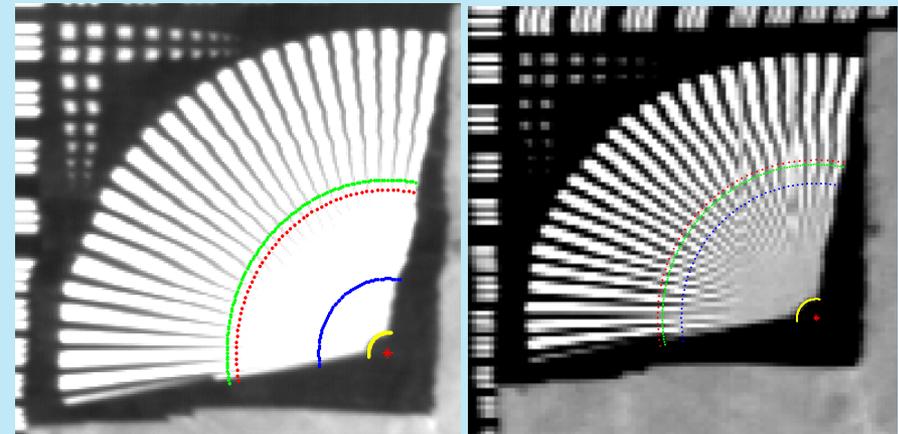
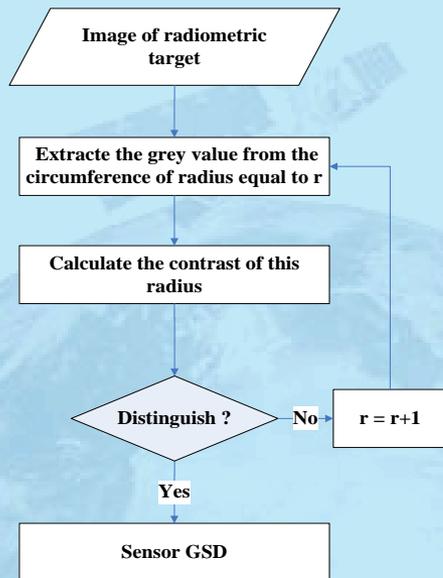
### 3. Inflight Calibration & Performance Assessment



- Cal&Val of Optical sensors – Geometric performance

#### Ground resolution

Defined as the least ground distance or the least size of object that can be distinguished.



Panchromatic image in 2011

Hyperspectral image in 2011

- Red line denotes the location of ground resolution estimated by our method.
- Blue line denotes the location of GSD.
- Green line denotes the location of ground resolution estimated by visual method.

Camera		Calculated Resolution (m)	Visual resolution (m)	GSD (m)
Panchromatic		0.7941	0.8153	0.35
Multispectral	B1	0.8889	0.8178	0.70
	B2	0.7800	0.8083	0.70
	B3	0.8875	0.8428	0.70
	B4	0.7500	0.7750	0.70

### 3. Inflight Calibration & Performance Assessment



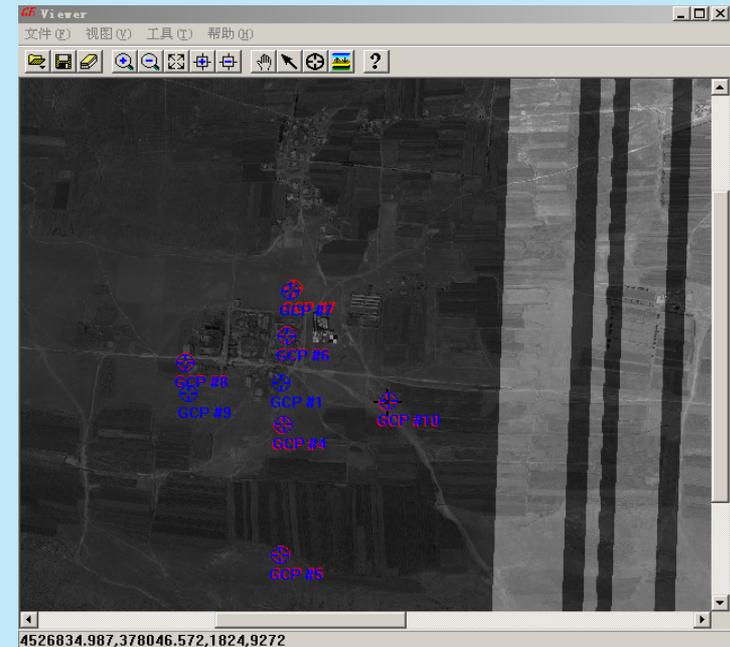
- Cal&Val of Optical sensors – Geometric performance

#### Geometric distortion

Geometric distortion evaluation result of panchromatic image in Sep. 2011 in Baotou city, China.

Data Type	External distortion Positioning error		Internal distortion	
	X-direction ( m )	Y-direction ( m )	Distance distortion ( m )	Angle distortion ( ° )
Geometric coarse correction	22.106	155.295	14.859	167.16
Geometric precision correction	0.568	1.012	0.866	0.085

Geometric distortion evaluation module

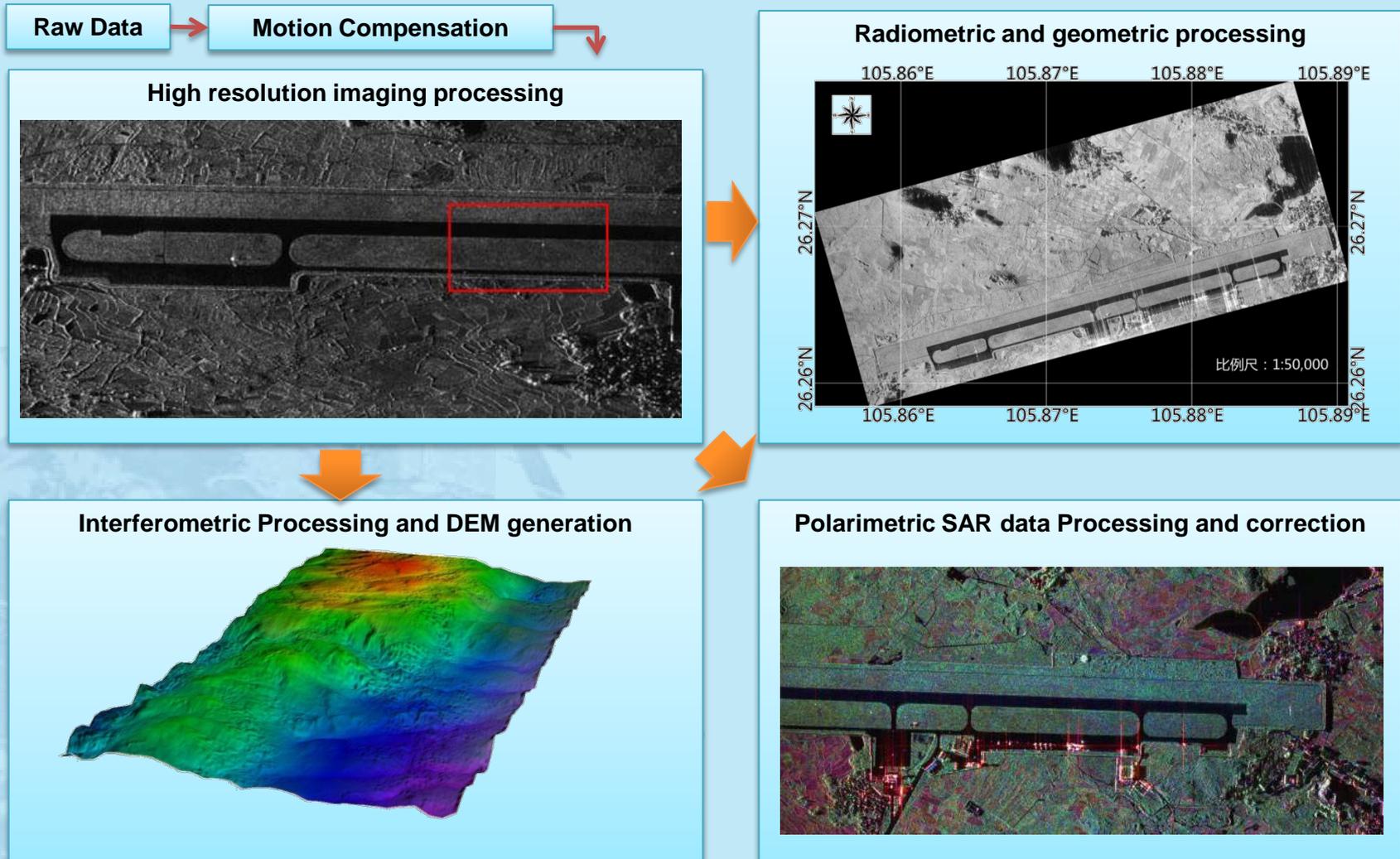


After geometric precision correction, the positioning accuracy can reach a meter-scale and the image distortion has also been corrected well.

# 3. Inflight Calibration & Performance Assessment



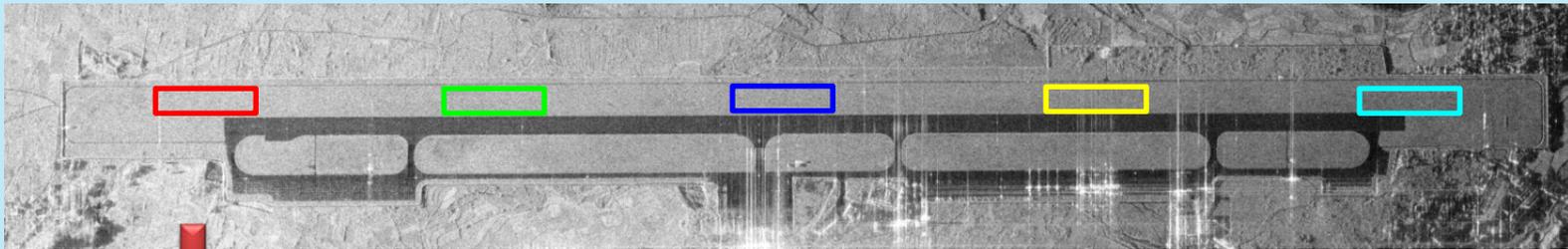
- Cal&Val of SAR sensors – SAR data processing system



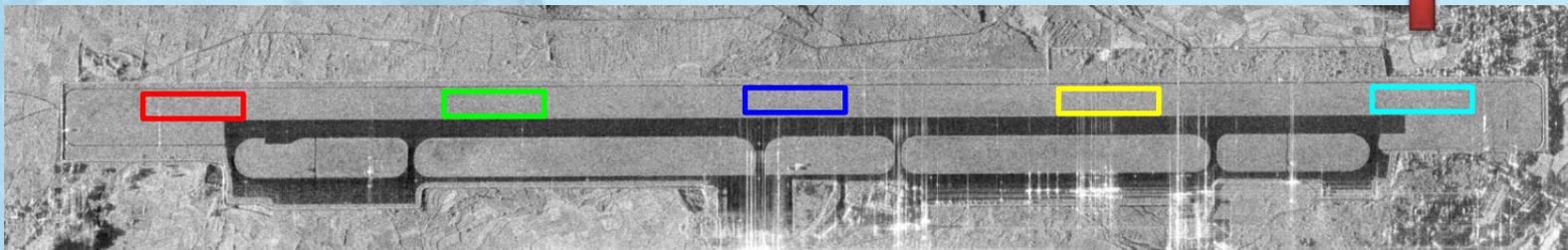
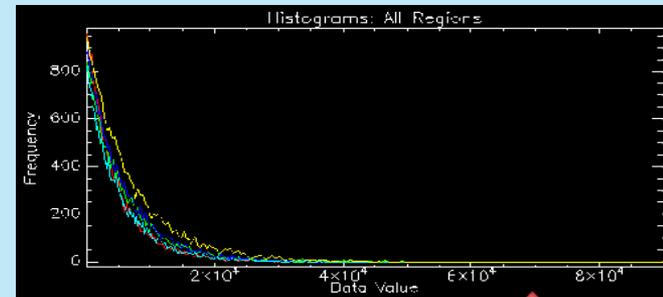
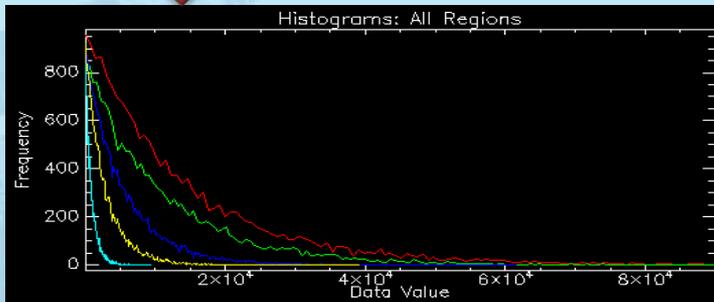
### 3. Inflight Calibration & Performance Assessment



- Cal&Val of SAR sensors – Relative radiometric calibration



Before relative radiometric calibration



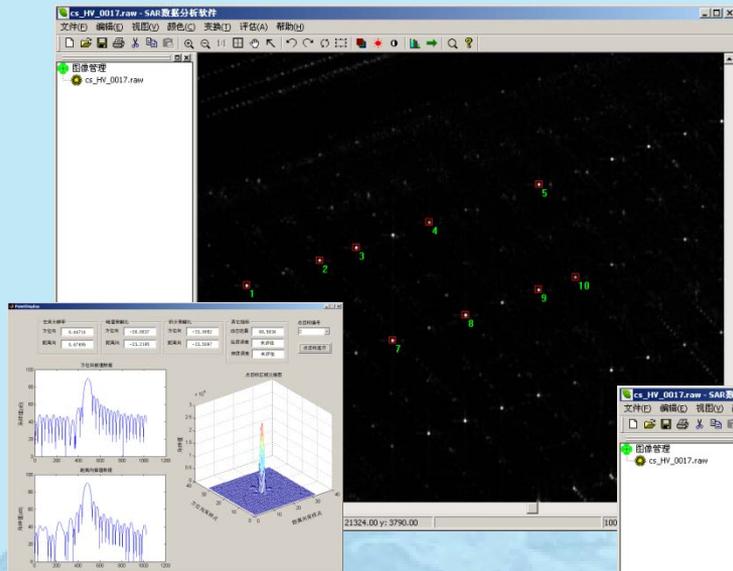
After relative radiometric calibration

# 3. Inflight Calibration & Performance Assessment



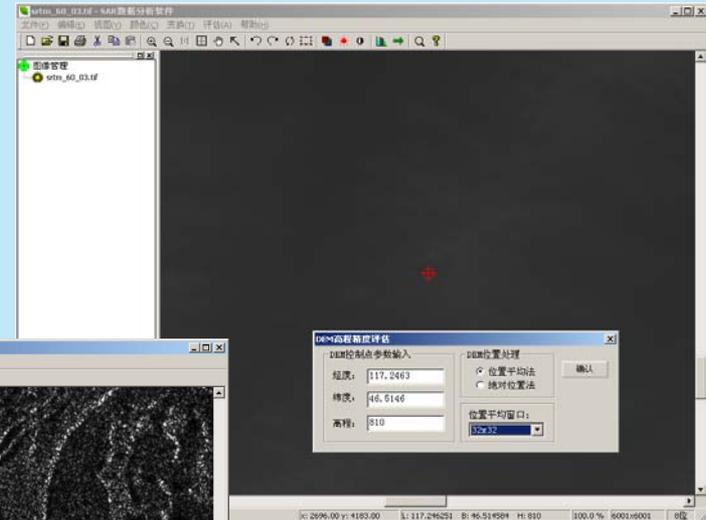
## Cal&Val of SAR sensors – data analyzing system

### Point target analysis



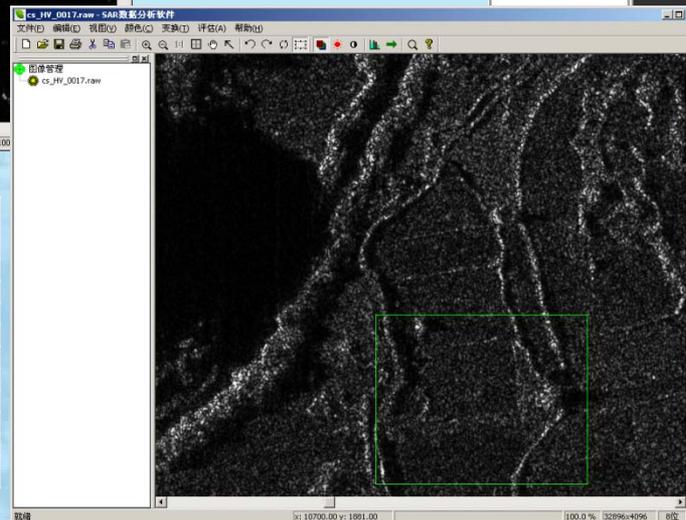
- Resolution
- PSLR(Peak Side Lobe Ratio)
- ISLR(Integrated Side Lobe Ratio)
- Dynamic range
- ....

### DEM analysis



- DEM accuracy

N o.	Az. Res. (m)	Rg. Res. (m)	Az. PSLR (dB)	Rg. PSLR (dB)	Az. ISLR (dB)	Rg. ISLR (dB)	Dy. Range (dB)
1	0.2997	0.2707	-29.9001	-24.3671	-30.5193	-25.5551	85.8664
2	0.2997	0.2804	-31.7376	-21.9761	-29.8146	-24.7290	85.2708
3	0.3045	0.2804	-29.2417	-22.0863	-29.5731	-25.9416	86.4129
4	0.2997	0.2852	-30.0977	-32.3270	-28.4382	-25.0391	82.5886
5	0.2997	0.2852	-31.9878	-21.1309	-29.6991	-19.2911	85.4210
6	0.3190	0.2852	-27.9996	-26.5897	-28.1798	-27.0331	77.4594
7	0.3094	0.2900	-30.4414	-23.3795	-29.8154	-26.2518	86.1319
8	0.2997	0.2755	-28.2101	-24.5004	-30.2793	-25.8863	87.7243
9	0.2997	0.2804	-28.7574	-26.5284	-29.1662	-27.6142	84.7408
0	0.3094	0.2852	-28.8182	-22.7427	-29.9757	-24.0932	81.8551



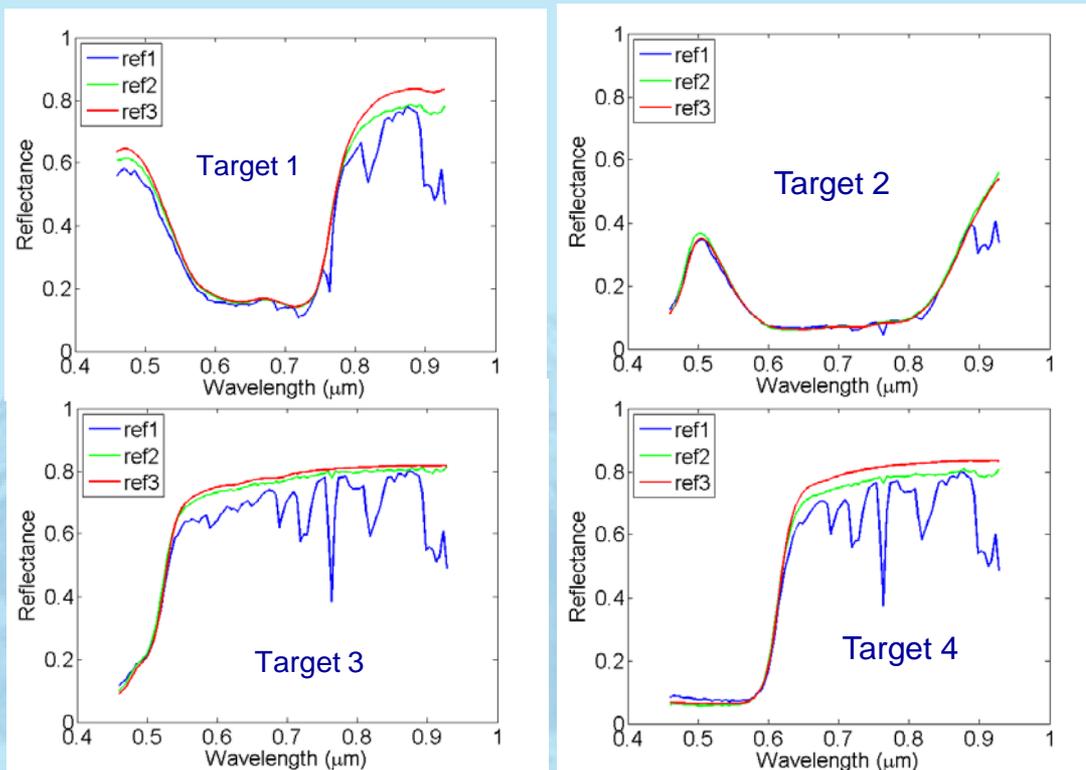
### Distributed target analysis

- ENL
- Radiometric resolution

### 3. Inflight Calibration & Performance Assessment



- Application performance – reflectance retrieval and validation
  - A Look Up Table (LUT) atmospheric correction model with adjacency effect correction was proposed to retrieve **land surface reflectance**.



Colored targets in red frame

ref1: at-sensor reflectance  
without atmospheric correction

ref2: surface reflectance after  
atmospheric correction

ref3: field measured reflectance

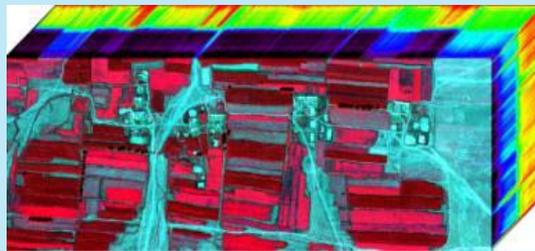
It can be seen that the proposed method can eliminate the atmospheric effect well.

### 3. Inflight Calibration & Performance Assessment

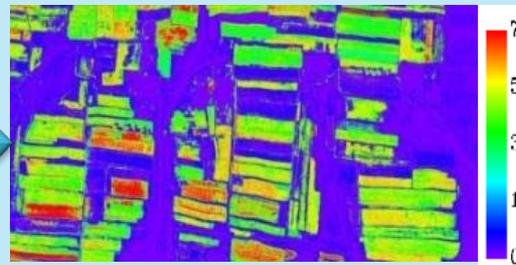


- Application performance – LAI retrieval and validation

- **Leaf Area Index (LAI)** was retrieved from hyperspectral data according to the image classification.

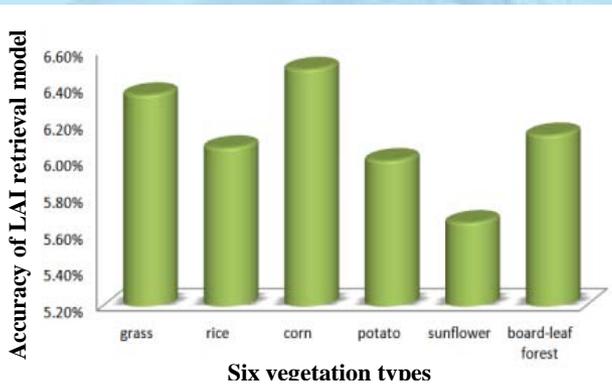


Retrieve

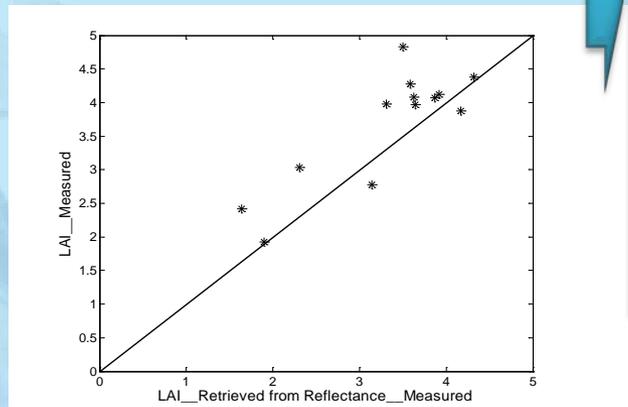


Airborne hyperspectral reflectance three-dimensional cube

Result of LAI retrieved



Accuracy of LAI retrieval model for six vegetation types



Accuracy assessment using field measurements on Sep 3, 2011.

- (1) Accuracy of LAI retrieval model is less than 7%.
- (2) Validation results show that the retrieval error of LAI is approximately 21.7% with field measurement data.
- (3) It might due to the retrieval error of reflectance, the saturation of NIR band with the increasing of LAI, the error of instruments.

# 4. Future Plan



A scenic view of a lake with pink cherry blossoms in the foreground and green hills in the background. The text "Thank you!" is overlaid in a white, cursive font with a black outline.

*Thank you!*