

*Develop a Generic Model for CEOS SI Traceable  
Cal/Val Sites*

*Sanya, China  
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# Outline

- Why SI traceable?
- Establishing and Assessing Claims
- Example Applications
- How to Prioritize Efforts?

# Why SI Traceable?

- Common measurement scale
  - Independent of measurement condition (time, space, source conditions, etc.)
  - Intercomparisons performed under controlled conditions
  - Results can be duplicated or improved as technology evolves
  - There is no physics without relevant measurement equations
- Good measurement practice
- Evaluation of uncertainty budget
- Documentation of measurement metrology
- Traceability ensures proper relation of national scales

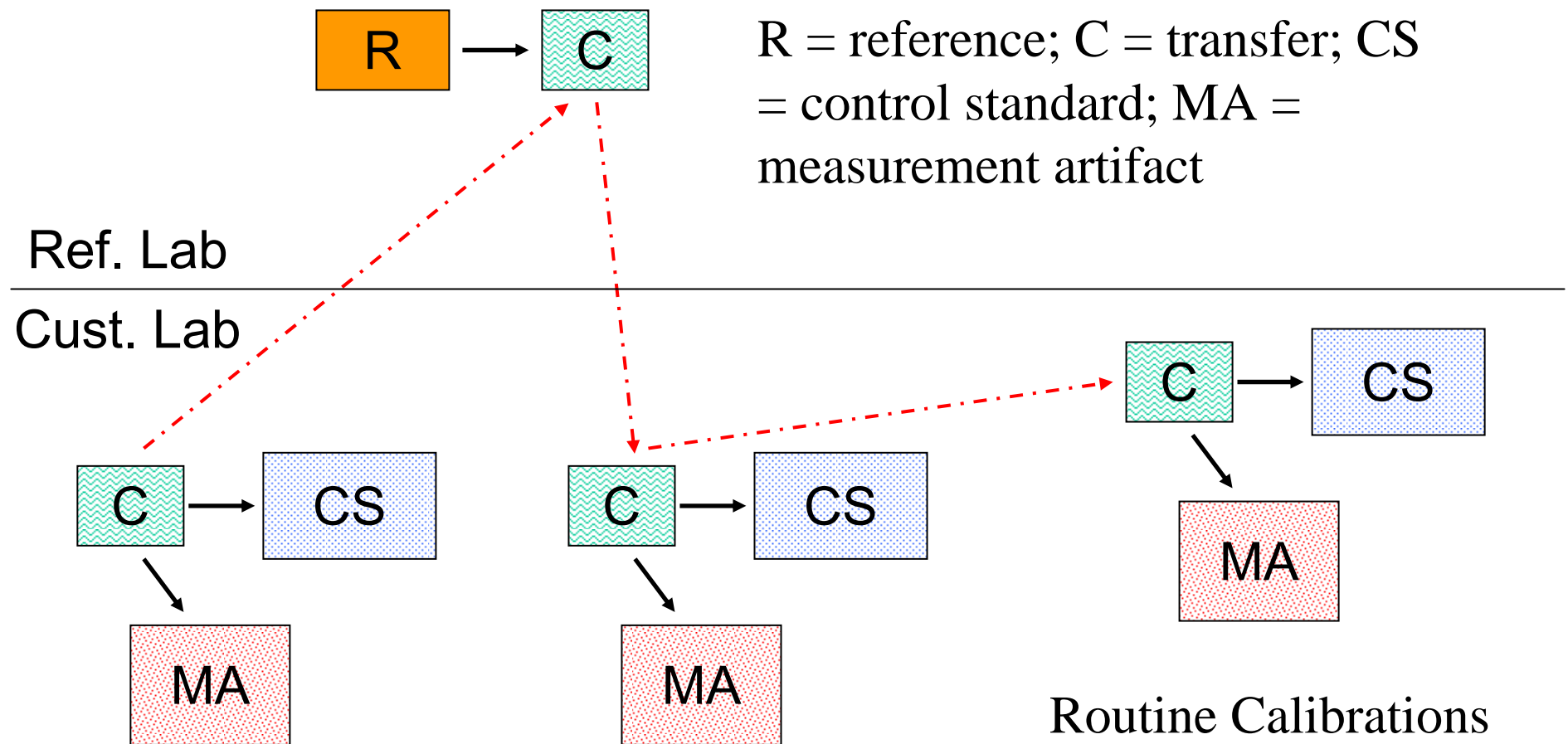
# Establishing Claims of Traceability (the supplier)

- Define what is measured, e.g.  $E_s(\lambda)$ ,  $L_u(\lambda)$
- Describe measurement system (ideally archival, peer-reviewed papers)
- Stated measurement result with documented uncertainties (web site, data archive)
- Description of stated reference (ideally archival, peer-reviewed papers)
- Internal Measurement Assurance Program (MAP) describing the status of the measurement system
- Internal MAP describing the status of the stated reference

# MAP Definition

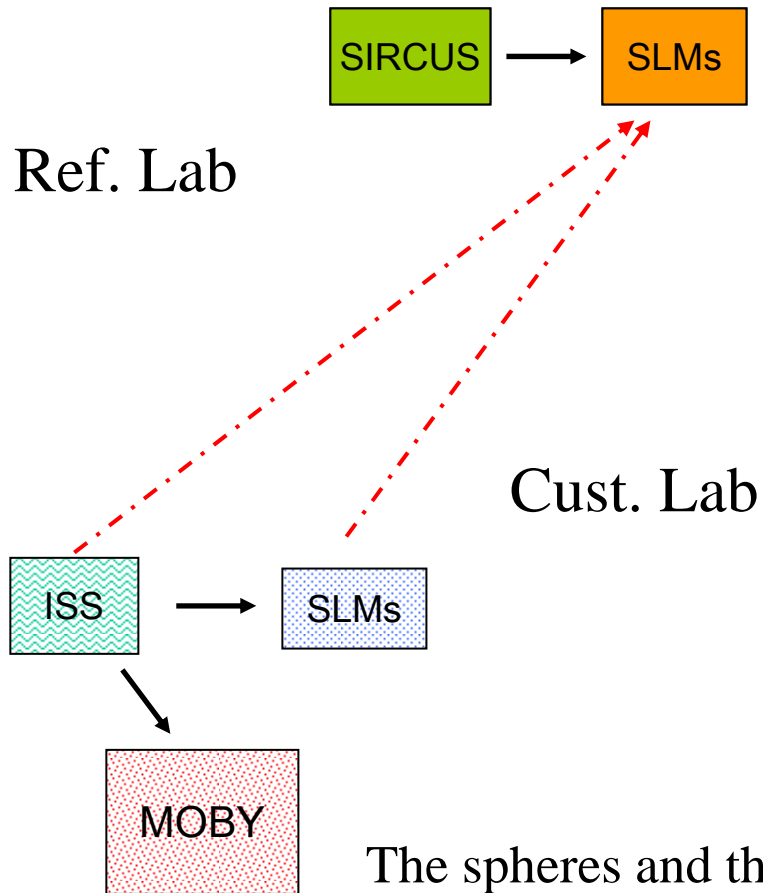
A program of sufficient complexity, within an organization, to provide credibility to the measurement uncertainty and measurement result for which traceability is to be established. An internal measurement assurance program usually involves monitoring the performance (e.g., stability, reproducibility) of the instrument, standard, or measurement system, both before and after it is characterized and calibrated, or used to obtain the traceable measurement result.

# Traceability through Calibration

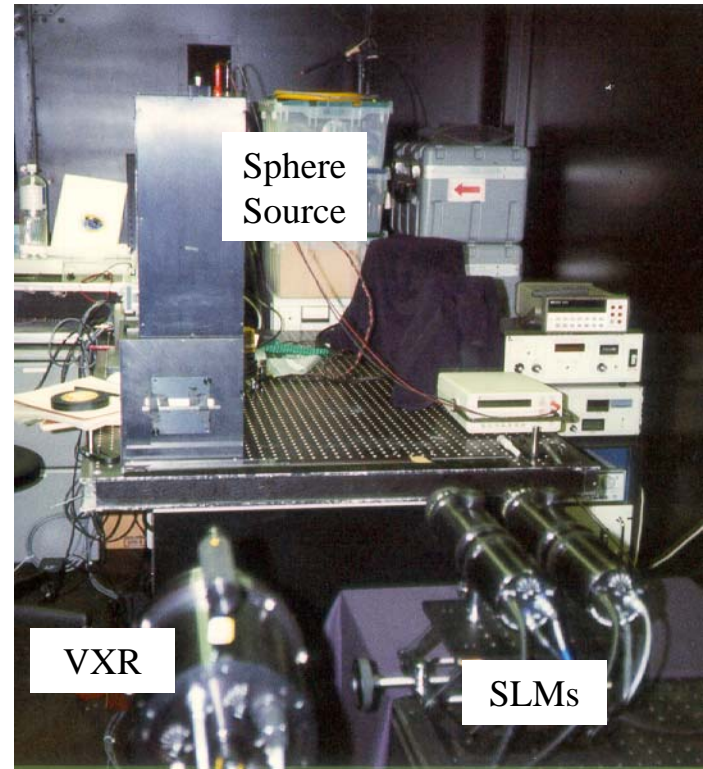


Internal MAP – execute before and after calibration

# MOBY Lu( $\lambda$ ) Example

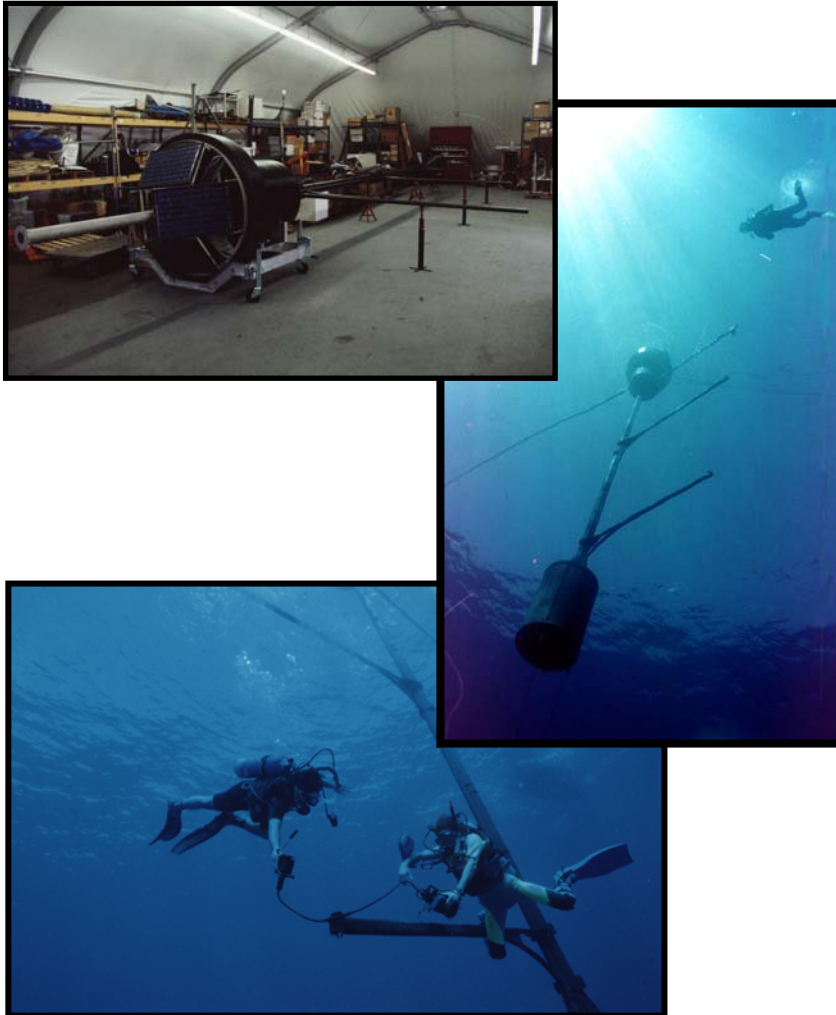


Calibration Hut, Honolulu



The spheres and the SLMs are sent to NIST. The SLMs measure the spheres every time the buoy is calibrated. The VXR is a separate validation (annually).

# MOBY Procedures



Rotate Buoy 4x/year

Pre- and Post Calibrations

E and L sources NIST-traceable

Sources recalibrated every 50 h

Sources verified during use with  
SLMs (NIST-designed radiometers)

Daily scans of three internal sources  
(blue and red LED; lamp)

Monthly measurements with stable,  
diver-deployed lamps

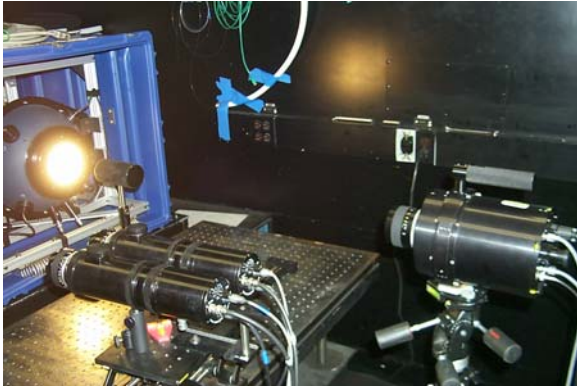
Detailed instrument characterization

Validation with independent artifacts

Site characterization



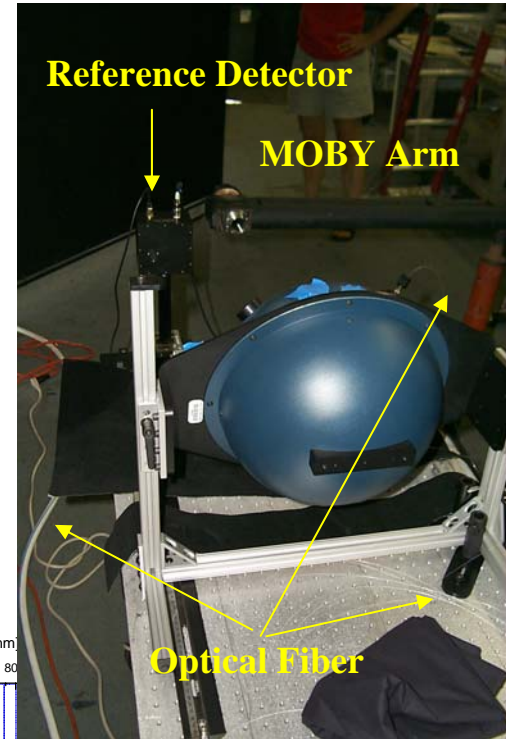
# Additional Cal/Val Elements



On-site measurements by NIST using NIST Portable Radiance (NPR) source and NIST/EOS Visible Transfer Radiometer (VXR) – performed annually



Cosine Response

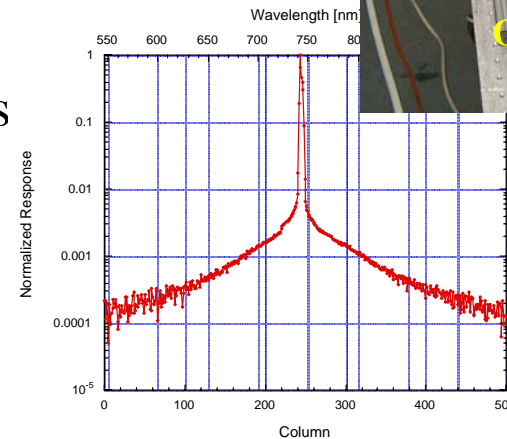


Reference Detector  
MOBY Arm  
Optical Fiber



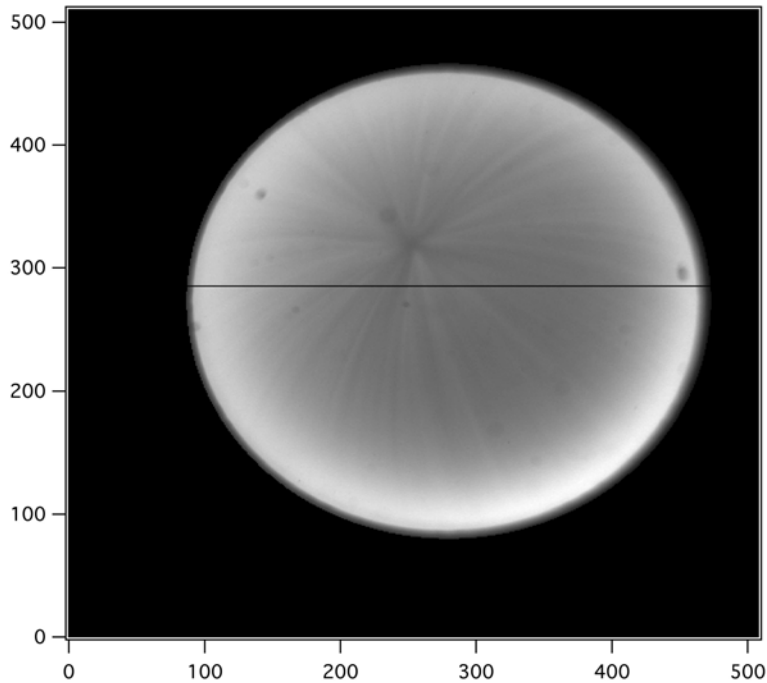
Ambient Temperature

Instrument Characterizations

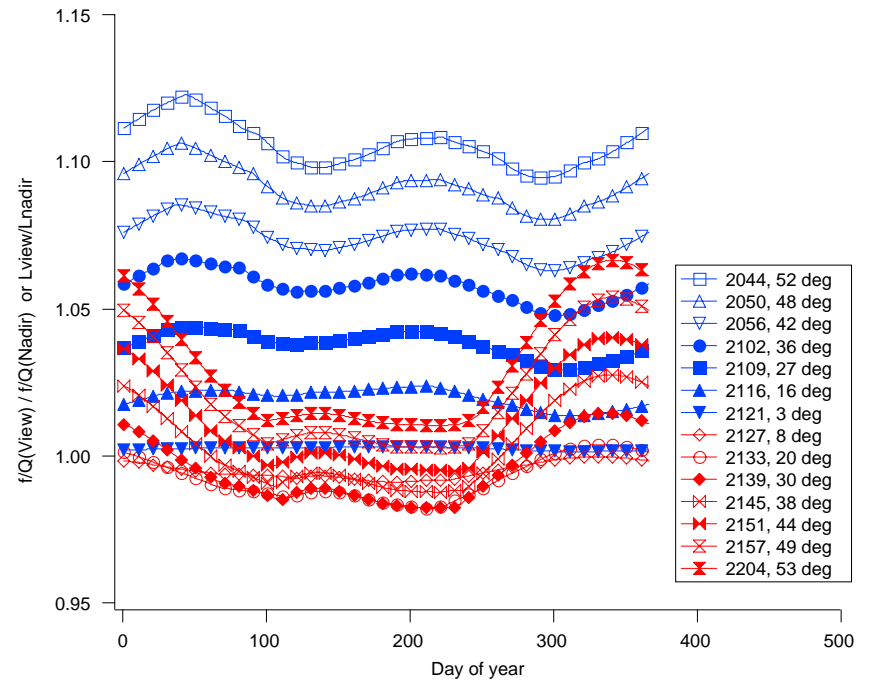


Stray light

# Site Characterization - BRDF



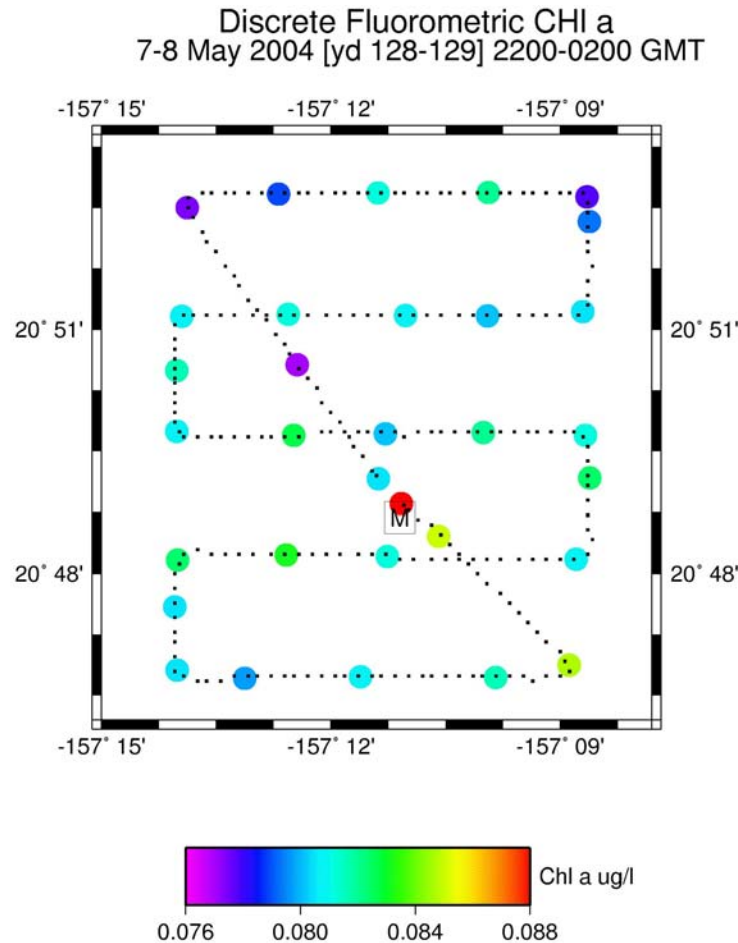
Upwelling Radiance Distribution (NuRADS)



Variation of  $L_{\text{view}}/L_{\text{nadir}}$  with day of year and scan time

# Site Characterization - Uniformity

Ship time is dedicated to mapping the ocean waters around MOBY for bio-optical properties.



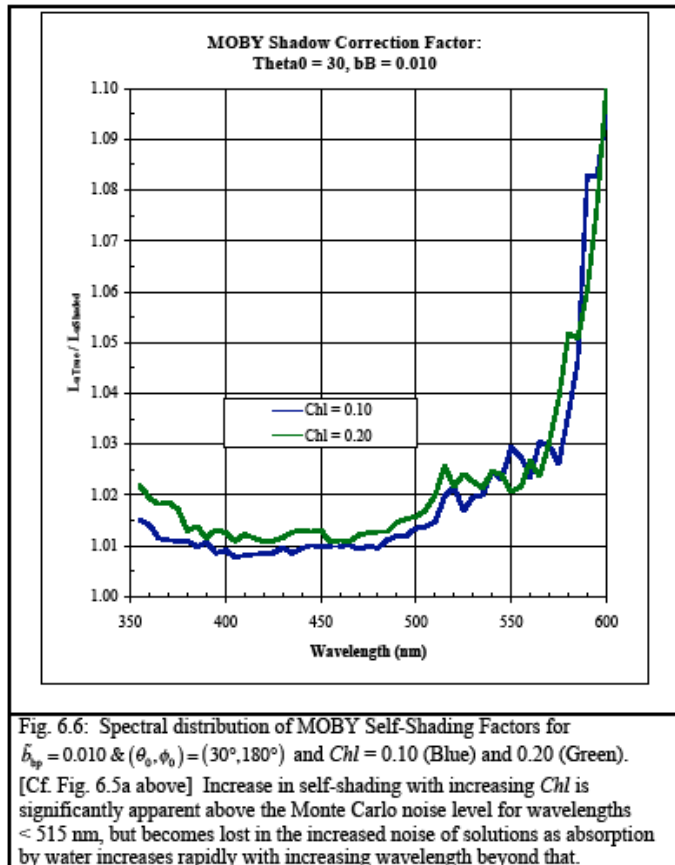
Std. D. =0.002  
Mean =0.081  
C.V. =2.6%



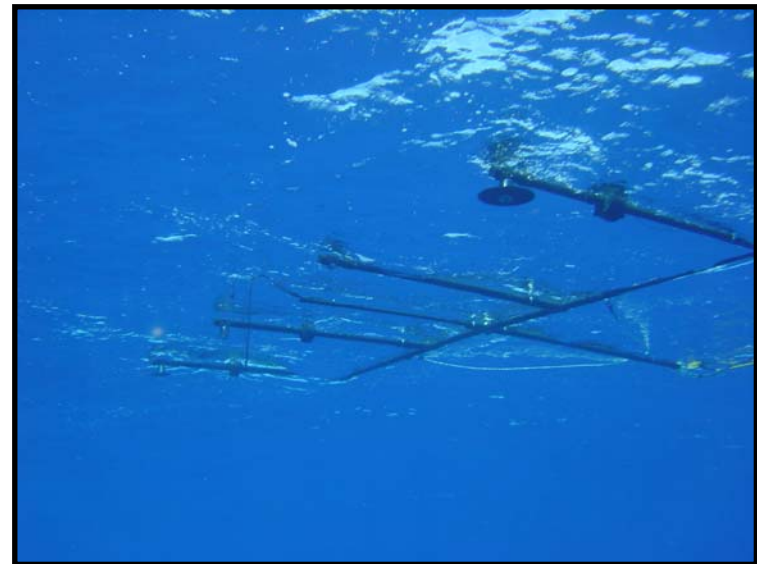
# Site Characterization – Self Shading

Final Report, NOAA Grant NA04NES4400007  
CHORS, San Diego State University Research Foundation

PI: James L. Mueller  
8/20/07



Theoretical and experimental approach is in progress; important for the red and near infrared spectral regions.



# Land Analogue

- Transfer artifacts (send to the reference lab):
  - FEL (irradiance lamps); diffuse reflectance standards (BRDF); radiometers (e.g., ASD)
- User calibration laboratory MAP: characterize field radiometers; calibrate with lab standard
- Field measurements:
  - the solar-illuminated reflectance standard is the reference standard;
  - site characterization is required.

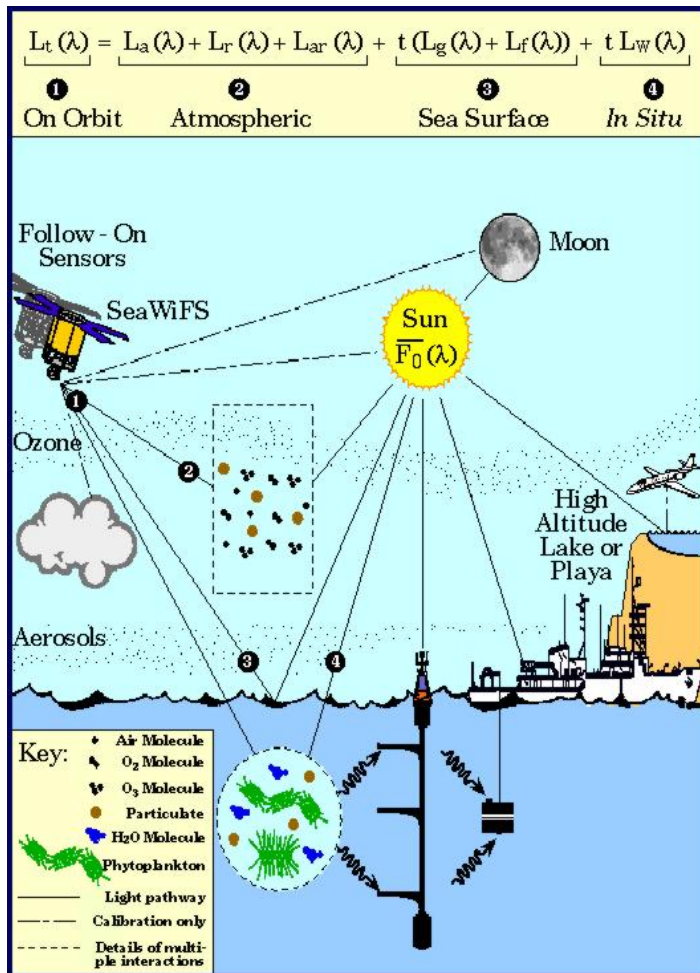
# Prioritize Efforts

- Perform measurement intercomparison
- Follow previous examples
  - UV downwelling spectral irradiance
  - SIRREX and SIMBIOS exercises
  - Ambient IR intercomparison (Miami)
  - Lunar Lake 1997 (laboratory effort tied to field program)
- Design experiments that identify instrument characterization issues

# Backup Slides



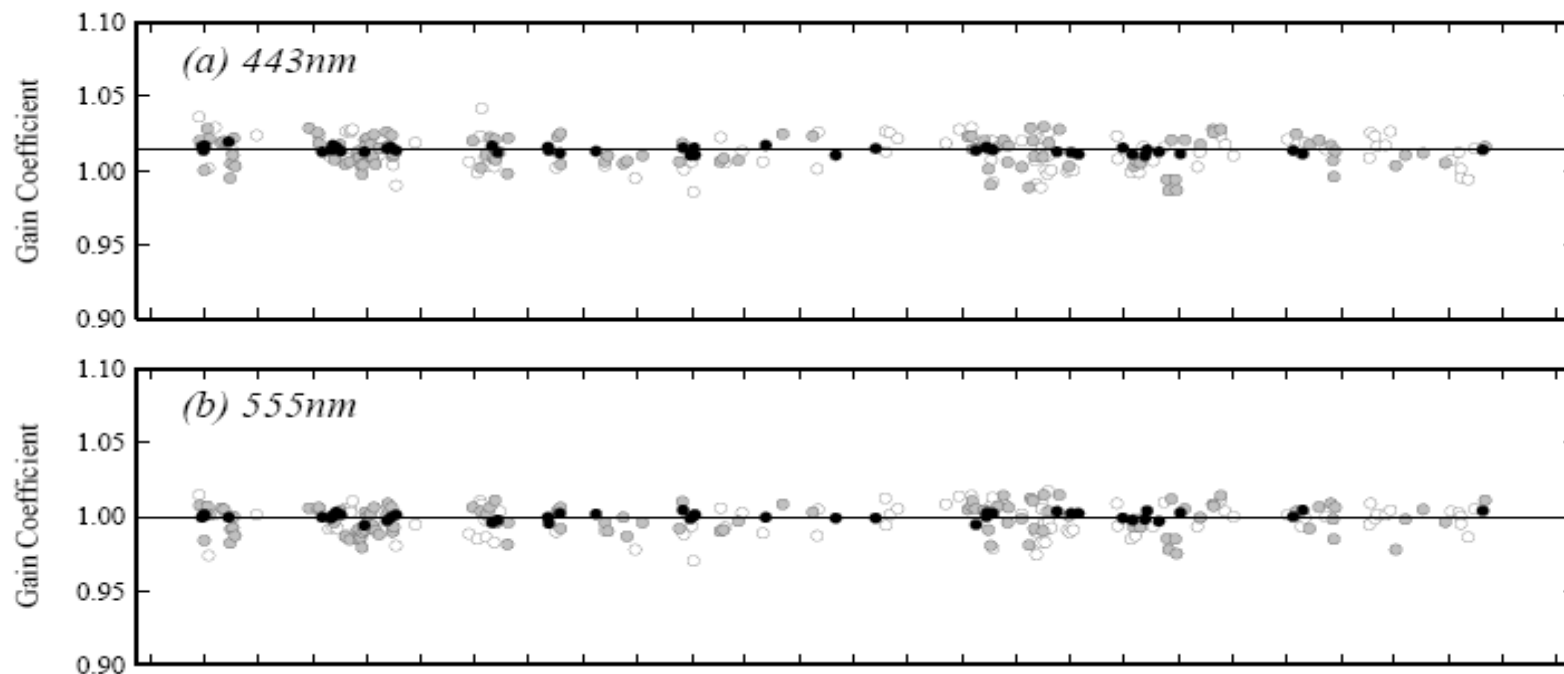
# Atmospheric Correction



In-water vicarious ocean color calibration utilizes the NIR channels of the satellite to determine atmospheric parameters.



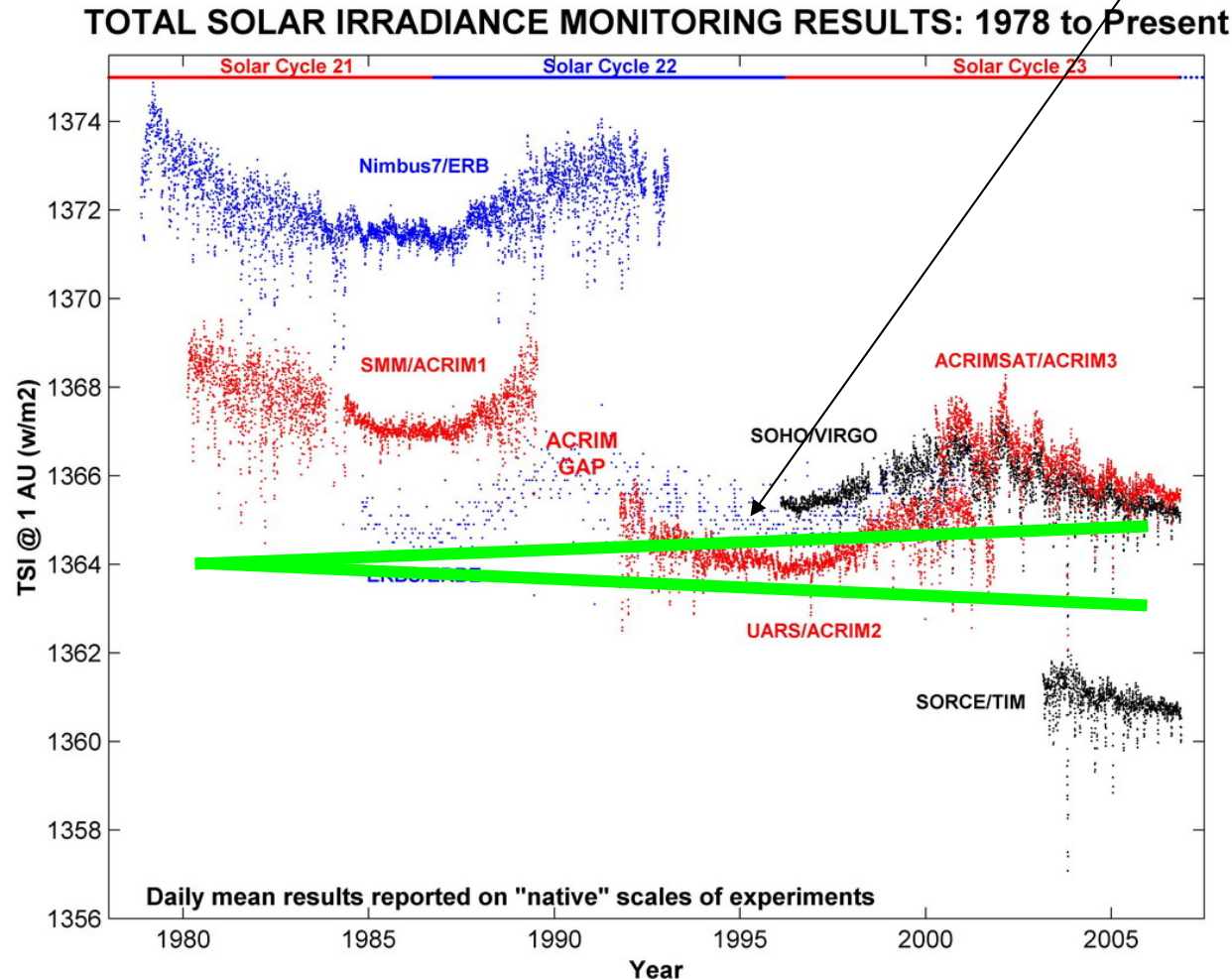
# Stability of MOBY Scale



Franz et al. 2007, Apl Opt Vol 46, No 22

# Total Solar Irradiance

**TSI Measurement Uncertainty Requirement ~ 0.02% ( $0.3 \text{ W m}^{-2}$ ) decade<sup>-1</sup>**



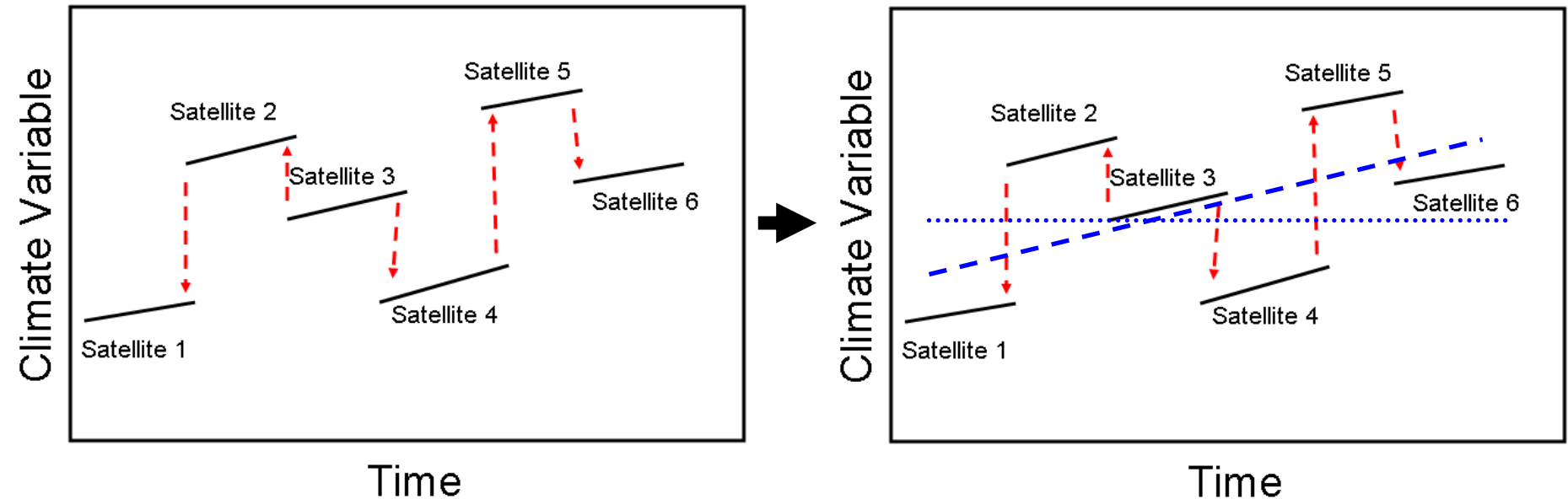
RC Willson, earth\_obs\_fig1 11/30/2006

If the spread is real, then TSI has changed  $< 1\%$  in 25 y. However, most of the differences must be measurement bias. There are also corrections for sensor degradation on orbit that are controversial.

None or  $\sim 0.5 \text{ W/m}^2$  change between solar minimum, depending on analysis.

Note – no uncertainties reported!

# Trending Through Sensor Overlap— Necessary But Not Sufficient

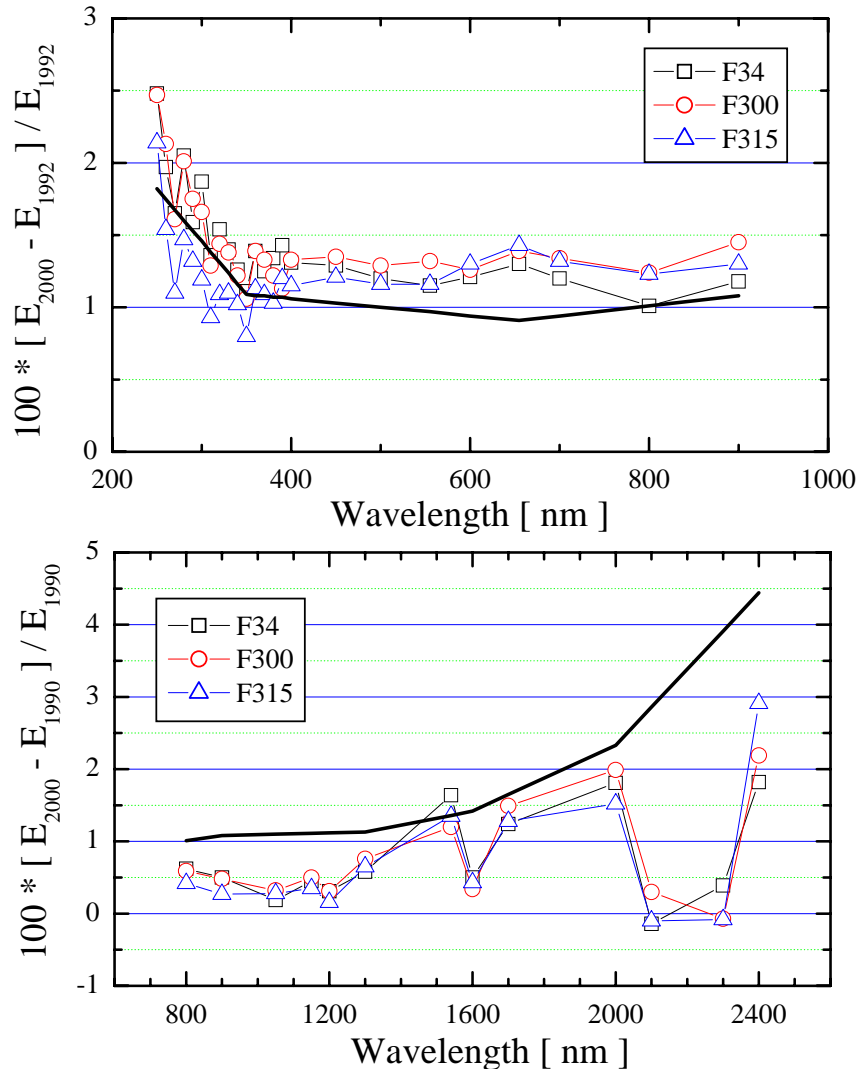


Observations using calibrated sensors.

Which composite is correct? Is there common instrument drift, climate change, or both?

**Sensor Drift: SI-based values (traceable) are essential; independent determinations required.**

# Scale Maintenance on Stable, Repeatable Artifacts – Necessary But Not Sufficient



## NIST Irradiance Scale Realization:

Source-Based: 1990 (NIR & SWIR) and 1992 (UV, VIS, & NIR)

Detector-Based: 2000 (UV to SWIR)

Expanded uncertainties are the solid lines

These check lamps held the previous scale very well; they are internally consistent ---

But, there was unknown bias in the previous scale that became obvious when the measurement metrology was changed.

## Intercompare Results!!

Not shown: Uncertainties were reduced by x2 to x10, depending on wavelength.