

### **Document Status**

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# **Document History**

Version	Date	Description of Change	Author
0.0.1	11.12.2020	Zero Draft translating previous materials to this format. With many thanks to all CEOS contributors.	Wang, Román
0.0.2	12.09.2020	Removed references to Black Marble to keep specification focused on the general measurement. Suggested acronym of Nighttime Light Surface Radiance (NLSR).	Killough
0.1.0	23.06.2022	Corrected references and author affiliation.	Ramachandran

# **Contributing Authors (in alphabetical order)**

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# Description

Product Family Title: Nighttime Light Surface Radiance (CARD4L-NLSR)

**Applies to:** Data collected with nighttime light sensors operating in the VIS/NIR wavelengths. These typically operate with ground sample distance and resolution in the order of 10-1000m; however, the Specification is not inherently limited to this resolution.

# Definitions

NLSR	Nighttime Light Surface Radiance
Ancillary Data	Data other than instrument measurements, originating in the instrument itself or from the satellite, required to perform processing of the data. They include orbit data, attitude data, time information, spacecraft engineering data, calibration data,

	data quality information, and data from other instruments.
Auxiliary Data	The data required for instrument processing, which does not originate in the instrument itself or from the satellite. Some auxiliary data will be generated in the ground segment, whilst other data will be provided from external sources.
Metadata	Structured information that describes other information or information services. With well-defined metadata, users should be able to get basic information about data, without the need to have knowledge about its entire content.
MTF	Modulation Transfer Function
Spectral Resolution	Defines the narrowest spectral feature that can be resolved by a spectrometer.
Spatial Resolution	The highest magnification of the sensor at the ground surface.
Spectral Sampling Distance	Spectral sampling is the interval, in wavelength units, between discrete data points in the measured spectrum.
Spatial Sampling Distance	Spatial sampling distance is the barycentre-to-barycentre distance between adjacent spatial samples on the Earth's surface.

# Requirements

#### **General Metadata**

These are metadata records describing a distributed collection of pixels. The collection of pixels referred to must be contiguous in space and time. General metadata should allow the user to assess the <u>overall</u> suitability of the dataset, and must meet the following requirements:

#	ltem	Threshold (Minimum) Requirements	Target (Desired) Requirements	Threshold Self-Assessment	Target Self-Assessment	Self-Assessment Explanation/ Justification	Recommended Requirement Modification
1.1	Traceability	Not required.	Data must be traceable to SI reference standard. Note 1: Relationship to 3.2. Traceability requires an estimate of measurement uncertainty. Note 2: Information on traceability should be available in the metadata as a single DOI landing page.				
1.2	Metadata Machine Readability	Metadata is provided in a structure that enables a computer algorithm to be used consistently and to automatically identify and extract each component part for further use.	As threshold, but metadata should be provided in a community endorsed standard that facilitates machine-readability, such as ISO 19115-2.				
1.3	Data Collection Time	The data collection time is identified in the metadata, expressed in date/time, to the second, with the time offset from UTC unambiguously identified.	Acquisition time for each pixel is identified (or can be reliably determined) in the metadata, expressed in date/time at UTC, to the second.				
1.4	Geographical Area	The surface location to which the data relates is identified, typically as a series of four corner points, expressed in an	The geographic area covered by the observations is identified specifically, such as through a set of coordinates				

#	Item	Threshold (Minimum) Requirements	Target (Desired) Requirements	Threshold Self-Assessment	Target Self-Assessment	Self-Assessment Explanation/ Justification	Recommended Requirement Modification
		accepted coordinate reference system (e.g., WGS84).	of a closely bounding polygon. The location to which each pixel refers is identified (or can be reliably determined) with the projection system (if any) and reference datum provided.				
1.5	Coordinate Reference System	The metadata lists the coordinate reference system that has been used.	As threshold.				
1.6	Map Projection	The metadata lists the map projection that has been used and any relevant parameters required in relation to use of data in that map projection.	As threshold.				
1.7	Geometric Correction Methods	Not required. The user is not explicitly advised of the geometric correction source and methods.	Information on geometric correction methods should be available in the metadata as a single DOI landing page, including reference database and auxiliary data such as elevation model(s) and reference chip-sets.				
1.8	Geometric Accuracy of the Data	Not required. The user is not provided with results of geometric accuracy assessments pertaining to the dataset.	The metadata includes metrics describing the assessed geodetic accuracy of the data, expressed units of the coordinate system of the data. Accuracy is assessed by independent verification (as well as internal model-fit where applicable). Uncertainties are expressed quantitatively, for example, as root mean square error				

#	Item	Threshold (Minimum) Requirements	Target (Desired) Requirements	Threshold Self-Assessment	Target Self-Assessment	Self-Assessment Explanation/ Justification	Recommended Requirement Modification
			(RMSE) or Circular Error Probability (CEP90, CEP95),				
			etc.				
			Note 1: Information on geometric accuracy of the				
			data should be available in				
			the metadata as a single DOI				
			landing page.				
			As threshold, but information				
			should be available in the				
		The instance and used to	metadata as a single DOI				
1.9	Instrument	The instrument used to	landing page with references				
1.9	Instrument	strument collect the data is identified in the metadata.	to the relevant CEOS				
			Missions, Instruments, and				
			Measurements Database				
			record.				
			As threshold, with instrument				
			spectral response details				
			(e.g., full spectral response				
			function) also included or				
		The control way along the for	directly accessible using details in the metadata.				
		The central wavelength for each band for which data is	Central wavelength and				
	Spectral	included is identified in the	bandwidth at full-width half				
1.10	Bands	metadata, expressed in SI	maximum value of the				
	Danus	units.	relative spectral response				
			function are provided at				
			least.				
			Note 1: Information on				
			spectral bands should be				
			available in the metadata as				
			a single DOI landing page.				
	Sensor	Not required.	Sensor calibration parameters				
1.11	Calibration	The general metadata does	are identified in the metadata				
	Calibration	not include sensor calibration	or can be accessed using				

#	Item	Threshold (Minimum) Requirements	Target (Desired) Requirements	Threshold Self-Assessment	Target Self-Assessment	Self-Assessment Explanation/ Justification	Recommended Requirement Modification
		details.	details included in the				
			metadata. Ideally this would				
			support machine-to-machine				
			access.				
			Note 1: Information on sensor				
			calibration should be				
			available in the metadata as				
			a single DOI landing page.				
			The metadata includes				
			metrics describing the				
			assessed absolute				
			radiometric uncertainty of				
			the version of the data or				
	Padiametric The gene	Not required. The general metadata does	product, expressed as				
			absolute radiometric				
			uncertainty relative to				
1.12		not include information on	appropriate, known reference				
1.12	Accuracy	the radiometric accuracy of	sites and standards (for				
		the data.	example, pseudo-invariant				
			calibration sites, rigorously				
			collected field spectra,				
			Rayleigh, DCC, etc.)				
			Note 1: Information on				
			radiometric accuracy should				
			be available in the metadata				
			as a single DOI landing page.				
		All algorithms, and the	As threshold, but only				
		sequence in which they were	algorithms that have been				
		applied in the generation	published in a peer-reviewed				
		process, are identified in the	journal.				
1.13	Algorithms	metadata. For example, these	Note 1: It is possible that high				
		may be available through	quality corrections are				
		Algorithm Theoretical Basis	applied through non-disclosed				
		documents.	processes. CARD4L does not				
		Note 1: Information on	per-se require full and open				

#	Item	Threshold (Minimum) Requirements	Target (Desired) Requirements	Threshold Self-Assessment	Target Self-Assessment	Self-Assessment Explanation/ Justification	Recommended Requirement Modification
		algorithms should be available in the metadata as a single DOI landing page.	data and methods. Note 2: Information on algorithms should be available in the metadata as a single DOI landing page.				
1.14	Auxiliary Data	The metadata identifies the sources of auxiliary data used in the generation process, ideally expressed as a single DOI landing page. <i>Note 1: Auxiliary data</i> <i>includes DEMs, aerosols, etc.</i> <i>data sources.</i>	As threshold, but information on auxiliary data should be available in the metadata as a single DOI landing page and is also available for free online download, contemporaneously with the product or through a link to the source.				
1.15	Processing Chain Provenance	Not required.	Information on processing chain provenance should be available in the metadata as a single DOI landing page containing detailed description of the processing steps used to generate the product, the organization that performed the processing, and the versions of software used, giving full transparency to the users.				
1.16	Data Access	Information on data access should be available in the metadata as a single DOI landing page. Note 1: Manual and offline interaction action (e.g., login) may be required.	As threshold.				

#	Item	Threshold (Minimum) Requirements	Target (Desired) Requirements	Threshold Self-Assessment	Target Self-Assessment	Self-Assessment Explanation/ Justification	Recommended Requirement Modification
1.17	Overall Data Quality	Not applicable.	<ul> <li>Machine-readable metrics describing the overall quality of the data are included in the metadata, at minimum the cloud cover extent, i.e.:</li> <li>Proportion of observations over land (c.f. ocean) affected by non- target phenomena, e.g., cloud and cloud shadows</li> </ul>				

#### **Per-Pixel Metadata**

The following minimum metadata specifications apply to each pixel. Whether the metadata are provided in a single record relevant to all pixels or separately for each pixel is at the discretion of the data provider. Per-pixel metadata should allow users to <u>discriminate between</u> (choose) observations on the basis of their individual suitability for application.

#	ltem	Threshold (Minimum) Requirements	Target (Desired) Requirements	Threshold Self-Assessment	Target Self-Assessment	Self-Assessment Explanation/ Justification	Recommended Requirement Modification
2.1	Metadata Machine Readability	Metadata is provided in a structure that enables a computer algorithm to be used to consistently and automatically identify and extract each component part for further use.	As threshold.				
2.2	No Data	Pixels that do not correspond to an observation ('empty pixels') are flagged.	As threshold.				
2.3	Incomplete Testing	The metadata identifies pixels for which the per-pixel tests (below) have not all been successfully completed. Note 1: This may be the result of missing ancillary data for a subset of the pixels.	The metadata identifies which tests have, and have not, been successfully completed for each pixel.				
2.4	Saturation	Metadata indicates where one or more spectral bands are saturated.	Metadata indicates which pixels are saturated for each spectral band.				
2.5	Cloud	Metadata indicates whether a pixel is assessed as being cloud.	As threshold, information on cloud detection should be available in the metadata as a single DOI landing page.				
2.6	Cloud Shadow	Not required.	Metadata indicates whether a pixel is assessed as being cloud shadow. Information on cloud shadow detection				

#	Item	Threshold (Minimum) Requirements	Target (Desired) Requirements	Threshold Self-Assessment	Target Self-Assessment	Self-Assessment Explanation/ Justification	Recommended Requirement Modification
			should be available in the metadata as a single DOI landing page.				
2.7	Land/Water Mask	Metadata indicates whether a pixel is land or water.	As threshold, information on land/water mask should be available in the metadata as a single DOI landing page.				
2.8	Snow/Ice Mask	Metadata indicates whether a pixel is snow/ice.	As threshold, information on snow/ice mask should be available in the metadata as a single DOI landing page.				
2.9	Terrain Shadow Mask	Not required.	The metadata indicates pixels that are not directly illuminated due to terrain shadowing.				
2.10	Terrain Occlusion	Not required.	The metadata indicates pixels that are not visible to the sensor due to terrain occlusion during off-nadir viewing.				
2.11	Lunar and Viewing Geometry	Provide average lunar and sensor viewing azimuth and zenith angles.	Provide per-pixel lunar and sensor viewing azimuth and zenith angles.				
2.12	Terrain Illumination Correction	Not required.	Coefficients used for terrain illumination correction are provided for each pixel.				
2.13	Aerosol Optical Depth Parameters	Not required.	To be determined.				
2.14	Moon Illumination Fraction	Provide average moon illumination fraction.	Provide per-pixel moon illumination fraction				
2.15	Brightness Temperature	Provide brightness temperature from thermal bands.	As threshold.				

#	ltem	Threshold (Minimum) Requirements	Target (Desired) Requirements	Threshold Self-Assessment	Target Self-Assessment	Self-Assessment Explanation/ Justification	Recommended Requirement Modification
2.16	Solar Zenith Angle	Provide solar zenith angle to support stray-light corrections (see also 3.6).	As threshold.				

#### **Radiometric and Atmospheric Corrections**

The following requirements must be met for all pixels in a collection. The requirements indicate both the necessary outcomes (3.1-3.3) and the minimum steps necessary to be deemed to have achieved those outcomes (3.4 onward). Radiometric corrections must lead to a valid measurement of surface reflectance.

#	ltem	Threshold (Minimum) Requirements	Target (Desired) Requirements	Threshold Self-Assessment	Target Self-Assessment	Self-Assessment Explanation/ Justification	Recommended Requirement Modification
3.1	Measurement	Pixel values that are expressed as a measurement of the nighttime light radiance.	Nighttime light radiance measurements are SI traceable (see also 1.1).				
3.2	Measurement Uncertainty	Not required. Note 1: In current practice, users determine fitness for purpose based on knowledge of the lineage of the data, rather than on a specific estimate of measurement uncertainty.	An estimate of the certainty of the values is provided in measurement units. Note 1: This is a requirement for SI traceability. See also 1.1. Note 2: Information on measurement uncertainty should be available in the metadata as a single DOI landing page.				
3.3	Measurement Normalisation	Not required.	Measurements are normalised for viewing conditions (i.e., nadir view angle). This may include radiative transfer modelling. <i>Note 1: Information on measurement normalisation should be available in the metadata as single DOI landing page.</i>				
3.4	Atmospheric Corrections	Corrections are applied for atmospheric scattering. Metadata contains a single	As threshold.				

#	Item	Threshold (Minimum) Requirements	Target (Desired) Requirements	Threshold Self-Assessment	Target Self-Assessment	Self-Assessment Explanation/ Justification	Recommended Requirement Modification
		<ul> <li>DOI landing page with references to: <ul> <li>a citable peer-reviewed algorithm</li> <li>technical documentation regarding the implementation of that algorithm</li> <li>the sources of ancillary data used to make corrections</li> </ul> </li> <li>Note 1: Examples of technical documentation include an Algorithm</li> <li>Theoretical Basis Document, product user guide, etc.</li> </ul>					
3.5	Lunar Radiance Corrections	Corrections are applied for lunar radiance. Metadata contains a single DOI landing page with references to: • a citable peer- reviewed algorithm • technical documentation regarding the implementation of that algorithm and the lunar model used. Note 1: Examples of	As threshold.				

#	ltem	Threshold (Minimum) Requirements	Target (Desired) Requirements	Threshold Self-Assessment	Target Self-Assessment	Self-Assessment Explanation/ Justification	Recommended Requirement Modification
		technical documentation include an Algorithm Theoretical Basis Document, product user guide, etc.					
3.6	Stray Light Corrections	Corrections are applied for stray light. Metadata contains a single DOI landing page with references to: • a citable peer- reviewed algorithm • technical documentation regarding the implementation of that algorithm and any models used. Note 1: Examples of technical documentation include an Algorithm Theoretical Basis Document, product user guide, etc.	As threshold.				

#### **Geometric Corrections**

Geometric corrections must place the measurement accurately on the surface of the Earth (that is, geolocate the measurement) allowing measurements taken through time to be compared.

#	ltem	Threshold (Minimum) Requirements	Target (Desired) Requirements	Threshold Self-Assessment	Target Self-Assessment	Self-Assessment Explanation/ Justification	Recommended Requirement Modification
4.1	Geometric Correction	Sub-pixel accuracy is achieved in <u>relative</u> geolocation, that is, the pixels from the same instrument and platform are consistently located, and are thus comparable, through time. Sub-pixel accuracy is taken to be less than or equal to 0.5- pixel radial root mean square error (rRMSE) or equivalent in Circular Error Probability (CEP) relative to a defined reference image. A consistent gridding/sampling frame is used, including common cell size, origin, and nominal sample point location within the cell (centre, II, ur). Relevant metadata must be provided under 1.8 and 1.9. Note 1: The threshold level will not necessarily enable interoperability between data from different sources as the geometric corrections for	Sub-pixel accuracy is achieved relative to an identified absolute independent terrestrial referencing system (such as a national map grid). A consistent gridding/sampling frame is necessary to meet this requirement. Relevant metadata must be provided under 1.8 and 1.9. Note 1: This requirement is intended to enable interoperability between imagery from different platforms that meet this level of correction and with non- image spatial data such as GIS layers and terrain models.				

each of the sources may			
differ.			

# Summary Self-Assessment Table

	Threshold	Target
1. General Metadata		
1.1 Traceability		
1.2 Metadata Machine Readability		
1.3 Data Collection Time		
1.4 Geographical Area		
1.5 Coordinate Reference System		
1.6 Map Projection		
1.7 Geometric Correction Methods		
1.8 Geometric Accuracy of the Data		
1.9 Instrument		
1.10 Spectral Bands		
1.11 Sensor Calibration		
1.12 Radiometric Accuracy		
1.13 Algorithms		
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1.15 Processing Chain Provenance		
1.16 Data Access		
1.17 Overall Data Quality		
2. Per-Pixel Metadata		
2.1 Metadata Machine Readability		
2.2 No Data		
2.3 Incomplete Testing		
2.4 Saturation		
2.5 Cloud		
2.6 Cloud Shadow		
2.7 Land/Water Mask		
2.8 Snow/Ice Mask		
2.9 Terrain Shadow Mask		
2.10 Terrain Occlusion		
2.11 Lunar and Viewing Geometry		
2.12 Terrain Illumination Correction		
2.13 Aerosol Optical Depth Parameters		
2.14 Moon Illumination Fraction		
2.15 Brightness Temperature		
2.16 Solar Zenith Angle		
3. Radiometric and Atmospheric Corrections		
3.1 Measurement		
3.2 Measurement Uncertainty		
3.3 Measurement Normalisation		
3.4 Atmospheric Corrections		
3.5 Lunar Radiance Corrections		
3.6 Stray Light Corrections		
4. Geometric Corrections		
4.1 Geometric Correction		

## Guidance

This section aims to provide background and specific information on the processing steps that can be used to achieve analysis ready data. This Guidance material does not replace or override the specifications.

### **Introduction to CARD4L**

#### What is CEOS Analysis Ready Data for Land (CARD4L) products?

CARD4L products have been processed to a minimum set of requirements and organized into a form that allows immediate analysis with a minimum of additional user effort. These products would be resampled onto a common geometric grid (for a given product) and would provide baseline data for further interoperability both through time and with other datasets.

CARD4L products are intended to be flexible and accessible products suitable for a wide range of users for a wide variety of applications, including particularly time series analysis and multi-sensor application development. They are also intended to support rapid ingestion and exploitation via high-performance computing, cloud computing and other future data architectures. They may not be suitable for all purposes and are not intended as a 'replacement' for other types of satellite products.

#### When can a product be called CARD4L?

The CARD4L branding is applied to a particular product once:

- the product has been assessed as meeting CARD4L requirements by the agency responsible for production and distribution of the product, and
- the assessment has been peer reviewed by the CEOS Land Surface Imaging Virtual Constellation in consultation with other CEOS working groups as appropriate, including the CEOS Working Group on Calibration and Validation.

Agencies or other entities considering undertaking an assessment process should contact the <u>Land</u> <u>Surface Imaging Virtual Constellation</u>.

A product can continue to use CARD4L branding as long as its generation and distribution remain consistent with the peer-reviewed assessment.

#### What is the difference between Threshold and Target?

Products that meet all threshold requirements should be immediately useful for scientific analysis or decision-making.

Products that meet target requirements will reduce the overall product uncertainties and enhance broad-scale applications. For example, the products may enhance interoperability or provide increased accuracy through additional corrections that are not reasonable at the *threshold* level.

Target requirements anticipate continuous improvement of methods and evolution of community expectations, which are both normal and inevitable in a developing field. Over time, *target* specifications may (and subject to due process) become accepted as *threshold* requirements.

### **Procedural Examples**

#### Processes to produce Threshold Nighttime Light Surface Radiance (NLSR) CARD4L:

The following correction processes would typically be applied to produce CARD4L-NLSR Threshold:

• No example processes are provided at this time.

The following additional processes could be applied to produce CARD4L-NLSR Target:

• No example processes are provided at this time.

## **Specific Examples**

#### Processes to produce Threshold Nighttime Light Surface Radiance CARD4L:

• No example processes are provided at this time.

### **Reference Papers**

The following papers provide scientific and technical guidance:

- Román, M.O., Wang, Z., Sun, Q., Kalb, V., Miller, S.D., Molthan, A., Schultz, L., Bell, J., Stokes, E.C., Pandey, B., Seto, K.C., Hall, D., Oda, T., Wolfe, R.E., Lin, G., Golpayegani, N., Devadiga, S., Davidson, C., Sarkar, S., Praderas, C., Schmaltz, J., Boller, R., Stevens, J., Ramos González, O.M., Padilla, E., Alonso, J., Detrés, Y., Armstrong, R., Miranda, I., Conte, Y., Marrero, N., MacManus, K., Esch, T., Masuoka, E.J., 2018. NASA's Black Marble nighttime lights product suite. Remote Sens. Environ. doi:10.1016/j.rse.2018.03.017
- Wang, Z., Román, M.O., Kalb, V.L., Miller, S.D., Zhang, J., Shrestha, R.M., 2021. Quantifying uncertainties in nighttime light retrievals from Suomi-NPP and NOAA-20 VIIRS Day/Night Band data. Remote Sens. Environ. 263. <u>doi:10.1016/j.rse.2021.112557</u>
- Mills, S., & Miller, S.D., 2014, October. VIIRS Day-Night Band (DNB) calibration methods for improved uniformity. In Earth Observing Systems XIX (Vol. 9218, p. 921809). International Society for Optics and Photonics.
- Ryan, R.E. et al., 2019. The Terra Vega Active Light Source: A First Step in a New Approach to Perform Nighttime Absolute Radiometric Calibrations and Early Results Calibrating the VIIRS DNB. *Remote Sens.* 2019, *11*, 710. <u>https://doi.org/10.3390/rs11060710</u>